NAG Fortran Library Routine Document H02BBF

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of **bold italicised** terms and other implementation-dependent details.

Warning. The specification of the parameters BIGBND and LIWORK changed at Mark 16: the 'default' value of the parameter BIGBND has been increased to 10^{20} and the minimum dimension of the array IWORK has been increased by N+3.

1 Purpose

H02BBF solves 'zero-one', 'general', 'mixed' or 'all' integer programming problems using a branch and bound method. The routine may also be used to find either the first integer solution or the optimum integer solution. It is not intended for large sparse problems.

2 Specification

```
SUBROUTINE HO2BBF(ITMAX, MSGLVL, N, M, A, LDA, BL, BU, INTVAR, CVEC,

MAXNOD, INTFST, MAXDPT, TOLIV, TOLFES, BIGBND, X,

OBJMIP, IWORK, LIWORK, RWORK, LRWORK, IFAIL)

INTEGER

ITMAX, MSGLVL, N, M, LDA, INTVAR(N), MAXNOD, INTFST,

MAXDPT, IWORK(LIWORK), LIWORK, LRWORK, IFAIL

real

A(LDA,*), BL(N+M), BU(N+M), CVEC(N), TOLIV, TOLFES,

BIGBND, X(N), OBJMIP, RWORK(LRWORK)
```

3 Description

H02BBF is capable of solving certain types of integer programming (IP) problems using a branch and bound (B&B) method, see Taha (1987). In order to describe these types of integer programs and to briefly state the B&B method, we define the following linear programming (LP) problem:

Minimize

$$F(x) = c_1 x_1 + c_2 x_2 + \ldots + c_n x_n$$

subject to

$$\sum_{j=1}^{n} a_{ij} x_j \begin{cases} = \\ \leq \\ \geq \end{cases} b_i, \quad i = 1, 2, \dots, m$$

$$l_j \le x_j \le u_j, \quad j = 1, 2, \dots, n \tag{1}$$

If, in (1), it is required that (some or) all the variables take integer values, then the integer program is of type (mixed or) all general IP problem. If additionally, the integer variables are restricted to take only 0-1 values (i.e., $l_i = 0$ and $u_i = 1$) then the integer program is of type (mixed or all) zero-one IP problem.

The B&B method applies directly to these integer programs. The general idea of B&B (for a full description see Dakin (1965) or Mitra (1973)) is to solve the problem without the integral restrictions as an LP problem (first *node*). If in the optimal solution an integer variable x_k takes a non-integer value x_k^* , two LP sub-problems are created by *branching*, imposing $x_k \leq [x_k^*]$ and $x_k \geq [x_k^*] + 1$ respectively, where $[x_k^*]$ denotes the integer part of x_k^* . This method of branching continues until the first integer solution (*bound*) is obtained. The hanging nodes are then solved and investigated in order to prove the optimality of the solution. At each node, an LP problem is solved using E04MFF/E04MFA.

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4 References

Taha H A (1987) Operations Research: An Introduction Macmillan, New York

Dakin R J (1965) A tree search algorithm for mixed integer programming problems Comput. J. 8 250-255

Mitra G (1973) Investigation of some branch and bound strategies for the solution of mixed integer linear programs *Math. Programming* **4** 155–170

5 Parameters

1: ITMAX – INTEGER

Input/Output

On entry: an upper bound on the number of iterations for each LP problem.

On exit: unchanged if on entry ITMAX > 0, else ITMAX = $max(50, 5 \times (N + M))$.

2: MSGLVL – INTEGER

Input

On entry: the amount of printout produced by H02BBF, as indicated below (see Section 5.1 for a description of the printed output). All output is written to the current advisory message unit (as defined by X04ABF).

Value Definition

- 0 No output.
- 1 The final IP solution only.
- 5 One line of output for each node investigated and the final IP solution.
- The original LP solution (first node), one line of output for each node investigated and the final IP solution.

3: N – INTEGER Input

On entry: n, the number of variables.

Constraint: N > 0.

4: M - INTEGER

Input

On entry: m, the number of general linear constraints.

Constraint: $M \ge 0$.

5: A(LDA,*) - real array

Input

Note: the second dimension of the array A must be at least N when M > 0, and at least 1 when M = 0.

On entry: the *i*th row of A must contain the coefficients of the *i*th general constraint, for i = 1, 2, ..., m.

If M = 0 then the array A is not referenced.

6: LDA – INTEGER

Input

On entry: the first dimension of the array A as declared in the (sub)program from which H02BBF is called.

Constraint: LDA $\geq \max(1, M)$.

7: BL(N+M) - real array

Input

8: BU(N+M) - real array

Input

On entry: BL must contain the lower bounds and BU the upper bounds, for all the constraints in the following order. The first n elements of each array must contain the bounds on the variables, and the next m elements the bounds for the general linear constraints (if any). To specify a non-existent

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lower bound (i.e., $l_j = -\infty$), set $BL(j) \le -BIGBND$ and to specify a non-existent upper bound (i.e., $u_j = +\infty$), set $BU(j) \ge BIGBND$. To specify the jth constraint as an equality, set $BL(j) = BU(j) = \beta$, say, where $|\beta| < BIGBND$.

Constraints:

$$BL(j) \le BU(j)$$
, for $j = 1, 2, ..., N + M$, $|\beta| < BIGBND$ when $BL(j) = BU(j) = \beta$.

9: INTVAR(N) – INTEGER array

Input

On entry: indicates which are the integer variables in the problem. For example, if x_j is an integer variable then INTVAR(j) must be set to 1, and 0 otherwise.

Constraints:

INTVAR
$$(j) = 0$$
 or 1 for $j = 1, 2, ..., N$, and INTVAR $(j) = 1$ for at least one value of j .

10: CVEC(N) - real array

Input

On entry: the coefficients c_j of the objective function $F(x) = c_1 x_1 + c_2 x_2 + \ldots + c_n x_n$. The routine attempts to find a minimum of F(x). If a maximum of F(x) is desired, CVEC(j) should be set to $-c_j$, for $j = 1, 2, \ldots, n$, so that the routine will find a minimum of -F(x).

11: MAXNOD – INTEGER

Input

On entry: the maximum number of nodes that are to be searched in order to find a solution (optimum integer solution). If MAXNOD ≤ 0 and INTFST ≤ 0 , then the B&B tree search is continued until all the nodes have been investigated.

12: INTFST – INTEGER

Input

On entry: specifies whether to terminate the B&B tree search after the first integer solution (if any) is obtained. If INTFST > 0 then the B&B tree search is terminated at node k say, which contains the first integer solution. For MAXNOD > 0 this applies only if $k \le MAXNOD$.

13: MAXDPT – INTEGER

Input

On entry: the maximum depth of the B&B tree used for branch and bound.

Suggested value: MAXDPT = $3 \times N/2$.

Constraint: MAXDPT ≥ 2 .

14: TOLIV – *real*

Input/Output

On entry: the integer feasibility tolerance; i.e., an integer variable is considered to take an integer value if its violation does not exceed TOLIV. For example, if the integer variable x_j is near unity then x_j is considered to be integer only if $(1 - \text{TOLIV}) \le x_j \le (1 + \text{TOLIV})$.

On exit: unchanged if on entry TOLIV > 0.0, else TOLIV = 10^{-5} .

15: TOLFES - real

Input/Output

On entry: the maximum acceptable absolute violation in each constraint at a 'feasible' point (feasibility tolerance); i.e., a constraint is considered satisfied if its violation does not exceed TOLFES.

On exit: unchanged if on entry TOLFES > 0.0, else TOLFES = $\sqrt{\epsilon}$ (where ϵ is the machine precision).

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16: BIGBND – real Input/Output

On entry: the 'infinite' bound size in the definition of the problem constraints. More precisely, any upper bound greater than or equal to BIGBND will be regarded as $+\infty$ and any lower bound less than or equal to -BIGBND will be regarded as $-\infty$.

On exit: unchanged if on entry BIGBND > 0.0, else BIGBND $= 10^{20}$.

17: X(N) - real array Input/Output

On entry: an initial estimate of the original LP solution.

On exit: with IFAIL = 0, X contains a solution which will be an estimate of either the optimum integer solution or the first integer solution, depending on the value of INTFST. If IFAIL = 9, then X contains a solution which will be an estimate of the best integer solution that was obtained by searching MAXNOD nodes.

18: OBJMIP – real Output

On exit: with IFAIL = 0 or 9, OBJMIP contains the value of the objective function for the IP solution.

19: IWORK(LIWORK) – INTEGER array

Workspace

20: LIWORK - INTEGER

Input

On entry: the dimension of the array IWORK as declared in the (sub)program from which H02BBF is called.

Constraint: LIWORK $\geq (25 + N + M) \times MAXDPT + 5 \times N + M + 4$.

21: RWORK(LRWORK) - real array

Workspace

22: LRWORK – INTEGER

Input

On entry: the dimension of the array RWORK as declared in the (sub)program from which H02BBF is called.

Constraint: LRWORK > MAXDPT \times (N + 1) + 2 \times MIN(N, M + 1)² + 14 \times N + 12 \times M.

If MSGLVL > 0, the amounts of workspace provided and required (with MAXDPT = $3 \times N/2$) are printed. As an alternative to computing MAXDPT, LIWORK and LRWORK from the formulas given above, the user may prefer to obtain appropriate values from the output of a preliminary run with the values of MAXDPT, LIWORK and LRWORK set to 1. If however only LIWORK and LRWORK are set to 1, then the appropriate values of these parameters for the given value of MAXDPT will be computed and printed unless MAXDPT < 2. In both cases H02BBF will then terminate with IFAIL = 6.

23: IFAIL – INTEGER Input/Output

On entry: IFAIL must be set to 0, -1 or 1. Users who are unfamiliar with this parameter should refer to Chapter P01 for details.

On exit: IFAIL = 0 unless the routine detects an error (see Section 6).

For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, because for this routine the values of the output parameters may be useful even if IFAIL $\neq 0$ on exit, the recommended value is -1. When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.

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5.1 Description of Printed Output

The level of printed output from H02BBF is controlled by the user (see the description of MSGLVL in Section 5).

When MSGLVL > 0, the summary printout at the end of execution of H02BBF includes a listing of the status of every variable and constraint. Note that default names are assigned to all variables and constraints. The following describes the printout for each variable.

Varbl gives the name (V) and index j, for j = 1, 2, ..., n of the variable.

State gives the state of the variable (FR if neither bound is in the working set, EQ if a

fixed variable, LL if on its lower bound, UL if on its upper bound, TF if temporarily fixed at its current value). If Value lies outside the upper or lower bounds by more than the **Feasibility Tolerance** (default value = $\sqrt{\epsilon}$, where ϵ is the *machine*

precision; see Section), State will be ++ or respectively.

Value is the value of the variable at the final iterate.

Lower Bound is the lower bound specified for the variable. (None indicates that

 $BL(j) \le -BIGBND$.) Note that if INTVAR(j) = 1, then the printed value of Lower Bound for the jth variable may not be the same as that originally supplied in

BL(j).

Upper Bound is the upper bound specified for the variable. (None indicates that

 $\mathrm{BU}(j) \geq \mathrm{BIGBND}$.) Note that if $\mathrm{INTVAR}(j) = 1$, then the printed value of Upper Bound for the jth variable may not be the same as that originally supplied in $\mathrm{BU}(j)$.

Lagr Mult is the value of the Lagrange multiplier for the associated bound constraint. This will

be zero if State is FR or TF. If x is optimal, the multiplier should be non-negative

if State is LL, and non-positive if State is UL.

Residual is the difference between the variable Value and the nearer of its bounds BL(j) and

BU(j).

The meaning of the printout for general constraints is the same as that given above for variables, with 'variable' replaced by 'constraint', BL(j) and BU(j) are replaced by BL(n+j) and BU(n+j) respectively, and with the following change in the heading.

L Con gives the name (L) and index j, for j = 1, 2, ..., m of the constraint.

When MSGLVL > 1, the summary printout at the end of every node during the execution of H02BBF is a listing of the outcome of forcing an integer variable with a non-integer value to take a value within its specified lower and upper bounds.

Node No is the current node number of the B&B tree being investigated.

Parent Node is the parent node number of the current node.

Obj Value is the final objective function value. If a node does not have a feasible solution then

No Feas Soln is printed instead of the objective function value. If a node whose optimum solution exceeds the best integer solution so far is encountered (i.e., it does not pay to explore the sub-problem any further), then its objective function value is

printed together with a CO (Cut Off).

Varbl Chosen is the index of the integer variable chosen for branching.

Value Before is the non-integer value of the integer variable chosen.

Lower Bound is the lower bound value that the integer variable is allowed to take.

Upper Bound is the upper bound value that the integer variable is allowed to take.

Value After is the value of the integer variable after the current optimization.

Depth is the depth of the B&B tree at the current node.

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6 Error Indicators and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

IFAIL = 1

No feasible integer point was found, i.e., it was not possible to satisfy all the integer variables to within the integer feasibility tolerance (determined by TOLIV). Increase TOLIV and rerun H02BBF.

IFAIL = 2

The original LP solution appears to be unbounded. This value of IFAIL implies that a step as large as BIGBND would have to be taken in order to continue the algorithm (see Section 8).

IFAIL = 3

No feasible point was found for the original LP problem, i.e., it was not possible to satisfy all the constraints to within the feasibility tolerance (determined by TOLFES). If the data for the constraints are accurate only to the absolute precision σ , the user should ensure that the value of the feasibility tolerance is greater than σ . For example, if all elements of A are of order unity and are accurate only to three decimal places, the feasibility tolerance should be at least 10^{-3} (see Section 8).

IFAIL = 4

The maximum number of iterations (determined by ITMAX) was reached before normal termination occurred for the original LP problem (see Section 8).

IFAIL = 5

Not used by this routine.

IFAIL = 6

An input parameter is invalid.

IFAIL = 7

The IP solution reported is not the optimum IP solution. In other words, the B&B tree search for at least one of the branches had to be terminated since an LP sub-problem in the branch did not have a solution (see Section 8).

IFAIL = 8

The maximum depth of the B&B tree used for branch and bound (determined by MAXDPT) is too small. Increase MAXDPT (along with LIWORK and/or LRWORK if appropriate) and rerun H02BBF.

IFAIL = 9

The IP solution reported is the best IP solution for the number of nodes (determined by MAXNOD) investigated in the B&B tree.

IFAIL = 10

No feasible integer point was found for the number of nodes (determined by MAXNOD) investigated in the B&B tree.

IFAIL = Overflow

It may be possible to avoid the difficulty by increasing the magnitude of the feasibility tolerance (TOLFES) and rerunning the program. If the message recurs even after this change, see Section 8.

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7 Accuracy

The routine implements a numerically stable active set strategy and returns solutions that are as accurate as the condition of the problem warrants on the machine.

8 **Further Comments**

The original LP problem may not have an optimum solution, i.e., H02BBF terminates with IFAIL = 2,3,4or overflow may occur. In this case, the user is recommended to relax the integer restrictions of the problem and try to find the optimum LP solution by using E04MFF/E04MFA instead.

In the B&B method, it is possible for an LP sub-problem to terminate without finding a solution. This may occur due to the number of iterations exceeding the maximum allowed. Therefore the B&B tree search for that particular branch cannot be continued. Thus the final IP solution reported is not the optimum IP solution (IFAIL = 7). For the second and unlikely case, a solution could not be found despite a second attempt at an LP solution.

9 **Example**

To solve the integer programming problem:

maximize

$$F(x) = 3x_1 + 4x_2$$

subject to the bounds

$$\begin{array}{l} x_1 \geq 0 \\ x_2 \geq 0 \end{array}$$

and to the general constraints

$$2x_1 + 5x_2 \le 15$$

$$2x_1 - 2x_2 \le 5$$

$$3x_1 + 2x_2 \ge 5$$

where x_1 and x_2 are integer variables.

The initial point, which is feasible, is

$$x_0 = (1,1)^{\mathrm{T}},$$

and $F(x_0) = 7$.

The optimal solution is

$$x^* = (2,2)^{\mathrm{T}},$$

and
$$F(x^*) = 14$$
.

Note that maximizing F(x) is equivalent to minimizing -F(x).

9.1 **Program Text**

Note: the listing of the example program presented below uses bold italicised terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
HO2BBF Example Program Text
```

Mark 16 Revised. NAG Copyright 1993.

.. Parameters ..

NIN, NOUT TNTEGER PARAMETER (NIN=5, NOUT=6)NMAX, MMAX INTEGER PARAMETER (NMAX=10,MMAX=10)

INTEGER T.DA

PARAMETER (LDA=MMAX) INTEGER LIWORK, LRWORK

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```
PARAMETER
                 (LIWORK=1000, LRWORK=1000)
.. Local Scalars ..
real
                  BIGBND, OBJMIP, TOLFES, TOLIV
INTEGER
                   I, IFAIL, INTFST, ITMAX, J, M, MAXDPT, MAXNOD,
                   MSGLVL, N
 .. Local Arrays ..
real
                   A(LDA, NMAX), BL(MMAX+NMAX), BU(MMAX+NMAX),
                   CVEC(NMAX), RWORK(LRWORK), X(NMAX)
INTEGER
                   INTVAR(NMAX), IWORK(LIWORK)
 .. External Subroutines ..
EXTERNAL
                  H02BBF
.. Executable Statements ..
WRITE (NOUT,*) 'HO2BBF Example Program Results'
Skip heading in data file
READ (NIN, *)
READ (NIN,*) N, M
IF (N.LE.NMAX .AND. M.LE.MMAX) THEN
    Read ITMAX, MSGLVL, MAXNOD, INTFST, MAXDPT, TOLFES, TOLIV,
    CVEC, A, BIGBND, BL, BU, INTVAR and X from data file
    READ (NIN, *) ITMAX, MSGLVL
   READ (NIN,*) MAXNOD
    READ (NIN,*) INTFST, MAXDPT
    READ (NIN,*) TOLFES, TOLIV
   READ (NIN,*) (CVEC(I),I=1,N)
READ (NIN,*) ((A(I,J),J=1,N),I=1,M)
   READ (NIN, *) BIGBND
    READ (NIN, \star) (BL(I), I=1, N+M)
    READ (NIN, \star) (BU(I), I=1, N+M)
    READ (NIN, *) (INTVAR(I), I=1, N)
   READ (NIN, \star) (X(I), I=1, N)
   Solve the IP problem
   IFAIL = -1
    CALL HO2BBF(ITMAX, MSGLVL, N, M, A, LDA, BL, BU, INTVAR, CVEC, MAXNOD,
                 INTEST, MAXDPT, TOLIV, TOLFES, BIGBND, X, OBJMIP, IWORK,
+
                 LIWORK, RWORK, LRWORK, IFAIL)
END IF
STOP
END
```

9.2 Program Data

```
HO2BBF Example Program Data
  2 3
                                                     :Values of N and M
  0 10
                                                     :Values of ITMAX and MSGLVL
                                                     :Value of MAXNOD
  0
  0 4
                                                     :Values of INTFST and MAXDPT
                                                     :Values of TOLFES and TOLIV
  0.0 0.0
 -3.0 -4.0
                                                     :End of CVEC
  2.0
       5.0
  2.0 -2.0
3.0 2.0
                                                     :End of matrix A
  1.0E+20
                                                     :Value of BIGBND
  0.0 0.0 -1.0E+20 -1.0E+20 5.0 :End of BL 1.0E+20 1.0E+20 15.0 5.0 1.0E+20 :End of BU
                                                      :End of INTVAR
  1
        1
  1.0
        1.0
                                                     :End of X
```

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9.3 Program Results

```
HO2BBF Example Program Results
```

*** H02BBF

*** Start of NAG Library implementation details ***

Implementation title: Generalised Base Version Precision: FORTRAN double precision

Product Code: FLBAS20D Mark: 20A

*** End of NAG Library implementation details ***

Parameters

Linear constraints Variables	3 2	First integ Max depth o		0	FF 4
Feasibility tolerance Infinite bound size		Print level EPS (machin			10 ·16
<pre>Integer feasibility tol. Max number of nodes</pre>		Iteration 1	imit.		50
** Workspace provided wit ** Workspace required wit		4: LRWORK = 4: LRWORK =			

*** Optimum LP solution *** -17.50000

V۵	arbl	State	Value	Lower Bound	Upper Bound	Lagr Mult	Residual
V V	1 2	FR FR	3.92857 1.42857	0.00000	None None	0.000	3.929 1.429
L	Con	State	Value	Lower Bound	Upper Bound	Lagr Mult	Residual
L L L	1 2 3	UL UL FR	15.0000 5.00000 14.6429	None None 5.00000	15.0000 5.00000 None	-1.000 -0.5000 0.000	0.000 -8.8818E-16 9.643

*** Start of tree search ***

Node	Parent	Obj		Varbl	Value	I	ower	Ţ	Upper	Value	Γ	epth
No	Node	Value		Chosen	Before	В	ound]	Bound	After		
2	1	No Feas	Soln	1	3.93	4	.00		None	4.00		1
3	1	-16.2		1	3.93	C	.00		3.00	3.00		1
4	3	-15.5		2	1.80	2	.00		None	2.00		2
5	3	-13.0		2	1.80	C	.00		1.00	1.00		2
	ا ما حاسا	~~~ ~~1+		de ale ale								

*** Integer solution ***

Node	Parent Node	Obj Value		Varbl	Value Before	Lower Bound	Upper Bound	Value After	Depth
No	Node	value		CHOSEH	реготе	boulia	boulla	Arter	
6	4	No Feas	Soln	1	2.50	3.00	3.00	3.00	3
7	4	-14.8		1	2.50	0.00	2.00	2.00	3
8	7	-12.0	CC	2	2.20	3.00	None	3.00	4
9	7	-14.0		2	2.20	2.00	2.00	2.00	4
	*** Inte	ger solut	tion 🖈	**					

*** End of tree search ***

Total of 9 nodes investigated.

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H02BBF

Exit HO2BBF - Optimum IP solution found.

Final IP objective value = -14.00000

Va	rbl	State	Value	Lower Bound	Upper Bound	Lagr Mult	Residual
V V	1 2	UL EQ	2.00000 2.00000	0.00000 2.00000	2.00000 2.00000	-3.000 -4.000	0.000
L	Con	State	Value	Lower Bound	Upper Bound	Lagr Mult	Residual

H02BBF.10 (last) [NP3546/20A]