NAG Fortran Library Routine Document

G02GCF

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of **bold italicised** terms and other implementation-dependent details.

1 Purpose

G02GCF fits a generalized linear model with Poisson errors.

2 Specification

```
SUBROUTINE GO2GCF(LINK, MEAN, OFFSET, WEIGHT, N, X, LDX, M, ISX, IP, Y,

WT, A, DEV, IDF, B, IRANK, SE, COV, V, LDV, TOL,

MAXIT, IPRINT, EPS, WK, IFAIL)

INTEGER

N, LDX, M, ISX(M), IP, IDF, IRANK, LDV, MAXIT, IPRINT,

IFAIL

real

X(LDX,M), Y(N), WT(*), A, DEV, B(IP), SE(IP),

COV(IP*(IP+1)/2), V(LDV,IP+7), TOL, EPS,

WK((IP*IP+3*IP+22)/2)

CHARACTER*1

LINK, MEAN, OFFSET, WEIGHT
```

3 Description

A generalized linear model with Poisson errors consists of the following elements:

(a) a set of n observations, y_i , from a Poisson distribution:

$$\frac{\mu^y e^{-\mu}}{u!}$$
.

- (b) X, a set of p independent variables for each observation, x_1, x_2, \ldots, x_p .
- (c) a linear model:

$$\eta = \sum \beta_j x_j.$$

- (d) a link between the linear predictor, η , and the mean of the distribution, μ , $\eta = g(\mu)$. The possible link functions are:
 - (i) exponent link: $\eta = \mu^a$, for a constant a,
 - (ii) identity link: $\eta = \mu$,
 - (iii) log link: $\eta = \log \mu$,
 - (iv) square root link: $\eta = \sqrt{\mu}$,
 - (v) reciprocal link: $\eta = \frac{1}{\mu}$.
- (e) a measure of fit, the deviance:

$$\sum_{i=1}^{n} \operatorname{dev}(y_i, \hat{\boldsymbol{\mu}}_i) = \sum_{i=1}^{n} 2\left(y_i \log\left(\frac{y_i}{\hat{\boldsymbol{\mu}}_i}\right) - (y_i - \hat{\boldsymbol{\mu}}_i)\right).$$

The linear parameters are estimated by iterative weighted least-squares. An adjusted dependent variable, z, is formed:

$$z = \eta + (y - \mu) \frac{\mathrm{d}\eta}{\mathrm{d}\mu}$$

and a working weight, w,

$$w = \left(\tau d \frac{\mathrm{d}\eta}{\mathrm{d}\mu}\right)^2,$$

where $\tau = \sqrt{\mu}$.

At each iteration an approximation to the estimate of β , $\hat{\beta}$, is found by the weighted least-squares regression of z on X with weights w.

G02GCF finds a QR decomposition of $w^{1/2}X$, i.e., $w^{1/2}X = QR$ where R is a p by p triangular matrix and Q is an n by p column orthogonal matrix.

If R is of full rank, then $\hat{\beta}$ is the solution to:

$$R\hat{\beta} = Q^T w^{1/2} z.$$

If R is not of full rank a solution is obtained by means of a singular value decomposition (SVD) of R.

$$R = Q_* \begin{pmatrix} D & 0 \\ 0 & 0 \end{pmatrix} P^T,$$

where D is a k by k diagonal matrix with non-zero diagonal elements, k being the rank of R and $w^{1/2}X$. This gives the solution

$$\hat{\beta} = P_1 D^{-1} \begin{pmatrix} Q_* & 0 \\ 0 & I \end{pmatrix} Q^T w^{1/2} z,$$

 P_1 being the first k columns of P, i.e., $P = (P_1 P_0)$.

The iterations are continued until there is only a small change in the deviance.

The initial values for the algorithm are obtained by taking

$$\hat{\eta} = g(y).$$

The fit of the model can be assessed by examining and testing the deviance, in particular by comparing the difference in deviance between nested models, i.e., when one model is a sub-model of the other. The difference in deviance between two nested models has, asymptotically, a χ^2 distribution with degrees of freedom given by the difference in the degrees of freedom associated with the two deviances.

The parameters estimates, $\hat{\beta}$, are asymptotically Normally distributed with variance-covariance matrix

$$C = R^{-1}R^{-1}$$
 in the full rank case, otherwise

$$C = P_1 D^{-2} P_1^T$$
.

The residuals and influence statistics can also be examined.

The estimated linear predictor $\hat{\eta} = X\hat{\beta}$, can be written as $Hw^{1/2}z$ for an n by n matrix H. The ith diagonal elements of H, h_i , give a measure of the influence of the ith values of the independent variables on the fitted regression model. These are known as leverages.

The fitted values are given by $\hat{\mu} = g^{-1}(\hat{\eta})$.

G02GCF also computes the deviance residuals, r:

$$r_i = \operatorname{sign}(y_i - \hat{\mu}_i) \sqrt{\operatorname{dev}(y_i, \hat{\mu}_i)}.$$

An option allows prior weights to be used with the model.

In many linear regression models the first term is taken as a mean term or an intercept, i.e., $x_{i,1} = 1$, for i = 1, 2, ..., n. This is provided as an option.

Often only some of the possible independent variables are included in a model; the facility to select variables to be included in the model is provided.

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If part of the linear predictor can be represented by a variables with a known coefficient then this can be included in the model by using an offset, o:

$$\eta = o + \sum \beta_j x_j.$$

If the model is not of full rank the solution given will be only one of the possible solutions. Other estimates may be obtained by applying constraints to the parameters. These solutions can be obtained by using G02GKF after using G02GCF. Only certain linear combinations of the parameters will have unique estimates, these are known as estimable functions, these can be estimated and tested using G02GNF.

Details of the SVD are made available in the form of the matrix P^* :

$$P^* = \begin{pmatrix} D^{-1}P_1^T \\ P_0^T \end{pmatrix}.$$

The generalized linear model with Poisson errors can be used to model contingency table data; see Cook and Weisberg (1982) and McCullagh and Nelder (1983).

4 References

Cook R D and Weisberg S (1982) Residuals and Influence in Regression Chapman and Hall

McCullagh P and Nelder J A (1983) Generalized Linear Models Chapman and Hall

Plackett R L (1974) The Analysis of Categorical Data Griffin

5 Parameters

1: LINK - CHARACTER*1

Input

On entry: indicates which link function is to be used.

If LINK = 'E', then an exponent link is used.

If LINK = 'I', then an identity link is used.

If LINK = 'L', then a log link is used.

If LINK = 'S', then a square root link is used.

If LINK = 'R', then a reciprocal link is used.

Constraint: LINK = 'E', 'I', 'L', 'S' or 'R'.

2: MEAN – CHARACTER*1

Input

On entry: indicates if a mean term is to be included.

If MEAN = 'M' (Mean), a mean term, intercept, will be included in the model.

If MEAN = 'Z' (Zero), the model will pass through the origin, zero-point.

Constraint: MEAN = 'M' or 'Z'.

3: OFFSET – CHARACTER*1

Input

On entry: indicates if an offset is required.

If OFFSET = 'Y', then an offset is required and the offsets must be supplied in the 7th column of V

If OFFSET = 'N', no offset is required.

Constraint: OFFSET = 'N' or 'Y'.

4: WEIGHT – CHARACTER*1

Input

On entry: indicates if weights are to be used.

If WEIGHT = 'U' (Unweighted), no prior weights are used.

If WEIGHT = 'W' (Weighted), prior weights are used and weights must be supplied in WT.

Constraint: WEIGHT = 'U' or 'W'.

5: N – INTEGER Input

On entry: the number of observations, n.

Constraint: $N \ge 2$.

6: X(LDX,M) - real array

Input

On entry: the matrix of all possible independent variables. X(i, j) must contain the ijth element of X, for i = 1, 2, ..., n; j = 1, 2, ..., M.

7: LDX – INTEGER Input

On entry: the first dimension of the array X as declared in the (sub)program from which G02GCF is called.

Constraint: $LDX \ge N$.

8: M – INTEGER Input

On entry: the total number of independent variables.

Constraint: $M \ge 1$.

9: ISX(M) – INTEGER array

Input

On entry: indicates which independent variables are to be included in the model.

If ISX(j) > 0, then the variable contained in the jth column of X is included in the regression model.

Constraints:

```
ISX(j) \ge 0, for j = 1, 2, ..., M, if MEAN = 'M', then exactly IP - 1 values of ISX must be > 0, if MEAN = 'Z', then exactly IP values of ISX must be > 0
```

10: IP – INTEGER Input

On entry: the number of independent variables in the model, including the mean or intercept if present.

Constraint: IP > 0.

11: Y(N) - real array

Input

On entry: observations on the dependent variable, y.

Constraint: $Y(i) \ge 0.0$, for i = 1, 2, ..., n.

12: WT(*) - real array

Input

On entry: if WEIGHT = 'W', then WT must contain the weights to be used in the weighted regression.

If WT(i) = 0.0, then the *i*th observation is not included in the model, in which case the effective number of observations is the number of observations with non-zero weights.

If WEIGHT = 'U', then WT is not referenced and the effective number of observations is n.

Constraint: if WEIGHT = 'W', WT(i) ≥ 0.0 , for i = 1, 2, ..., n.

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13: A - real Input

On entry: if LINK = 'E', then A must contain the power of the exponential.

If LINK \neq 'E', A is not referenced.

Constraint: if LINK = 'E', $A \neq 0.0$.

14: DEV – real Output

On exit: the deviance for the fitted model.

15: IDF – INTEGER Output

On exit: the degrees of freedom associated with the deviance for the fitted model.

16: B(IP) - real array Output

On exit: the estimates of the parameters of the generalized linear model, $\hat{\beta}$.

If MEAN = 'M', then the first element of B will contain the estimate of the mean parameter and B(i+1) will contain the coefficient of the variable contained in column j of X, where ISX(j) is the ith positive value in the array ISX.

If MEAN = 'Z', then B(i) will contain the coefficient of the variable contained in column j of X, where ISX(j) is the ith positive value in the array ISX.

17: IRANK – INTEGER Output

On exit: the rank of the independent variables.

If the model is of full rank, then IRANK = IP.

If the model is not of full rank, then IRANK is an estimate of the rank of the independent variables. IRANK is calculated as the number of singular values greater that EPS×(largest singular value). It is possible for the SVD to be carried out but for IRANK to be returned as IP.

18: SE(IP) - real array Output

On exit: the standard errors of the linear parameters.

SE(i) contains the standard error of the parameter estimate in B(i), for i = 1, 2, ..., IP.

19: COV(IP*(IP+1)/2) - real array Output

On exit: the upper triangular part of the variance-covariance matrix of the IP parameter estimates given in B. They are stored packed by column, i.e., the covariance between the parameter estimate given in B(i) and the parameter estimate given in B(j), $j \ge i$, is stored in $COV(j \times (j-1)/2 + i)$.

20: V(LDV,IP+7) - real array Input/Output

On entry: if OFFSET = 'N', V need not be set.

If OFFSET = 'Y', V(i,7), for $i=1,2,\ldots,n$ must contain the offset values o_i . All other values need not be set.

On exit: auxiliary information on the fitted model.

- V(i,1) contains the linear predictor value, η_i , for $i=1,2,\ldots,n$.
- V(i,2) contains the fitted value, $\hat{\mu}_i$, for $i=1,2,\ldots,n$.
- V(i,3) contains the variance standardization, $\frac{1}{\tau}$, for $i=1,2,\ldots,n$.
- V(i,4) contains the square root of the working weight, $w_i^{\frac{1}{2}}$, for $i=1,2,\ldots,n$.
- V(i,5) contains the deviance residual, r_i , for i = 1, 2, ..., n.
- V(i,6) contains the leverage, h_i , for i = 1, 2, ..., n.

V(i,7) contains the offset, o_i , for $i=1,2,\ldots,n$. If OFFSET = 'N', then all values will be zero.

V(i,j) for $j=8,\ldots,IP+7$, contains the results of the QR decomposition or the singular value decomposition. If the model is not of full rank, i.e., IRANK < IP, then the first IP rows of columns 8 to IP + 7 contain the P^* matrix.

21: LDV – INTEGER Input

On entry: the dimension of the array V as declared in the (sub)program from which G02GCF is called

Constraint: LDV \geq N.

22: TOL – real Input

On entry: indicates the accuracy required for the fit of the model.

The iterative weighted least-squares procedure is deemed to have converged if the absolute change in deviance between iterations is less than $TOL \times (1.0 + Current Deviance)$. This is approximately an absolute precision if the deviance is small and a relative precision if the deviance is large.

If $0.0 \le TOL < machine precision$, then the routine will use $10 \times machine precision$ instead.

Constraint: $TOL \geq 0.0$.

23: MAXIT – INTEGER Input

On entry: the maximum number of iterations for the iterative weighted least-squares.

If MAXIT = 0, then a default value of 10 is used.

Constraint: MAXIT ≥ 0 .

24: IPRINT – INTEGER Input

On entry: indicates if the printing of information on the iterations is required.

If IPRINT ≤ 0 , then there is no printing.

If IPRINT > 0, then every IPRINT iteration, the following are printed:

the deviance:

the current estimates;

and if the weighted least-squares equations are singular then this is indicated.

When printing occurs the output is directed to the current advisory message unit (see X04ABF).

25: EPS – real Input

On entry: the value of EPS is used to decide if the independent variables are of full rank and, if not, what is the rank of the independent variables. The smaller the value of EPS the stricter the criterion for selecting the singular value decomposition.

If $0.0 \le EPS < machine precision$, then the routine will use machine precision instead.

Constraint: EPS ≥ 0.0 .

26: WK((IP*IP+3*IP+22)/2) - real array Workspace

27: IFAIL – INTEGER Input/Output

On entry: IFAIL must be set to 0, -1 or 1. Users who are unfamiliar with this parameter should refer to Chapter P01 for details.

On exit: IFAIL = 0 unless the routine detects an error (see Section 6).

For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, because for this routine the values of the output parameters

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may be useful even if IFAIL $\neq 0$ on exit, the recommended value is -1. When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.

6 Error Indicators and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

```
IFAIL = 1
      On entry, N < 2,
                M < 1,
      or
                LDX < N,
      or
                LDV < N,
      or
      or
                IP < 1,
                LINK \neq 'E', 'I', 'L', 'S' or 'R',
      or
                LINK = 'E' and A = 0.0,
      or
                MEAN \neq 'M' or 'Z',
      or
                WEIGHT \neq 'U' or 'W'.
      or
                OFFSET \neq 'N' or 'Y',
      or
                MAXIT < 0,
      or
                TOL < 0.0,
      or
                EPS < 0.0.
      or
IFAIL = 2
      On entry, WEIGHT = 'W' or 'V' and a value of WT < 0.0.
IFAIL = 3
      On entry, a value of ISX < 0,
                the value of IP is incompatible with the values of MEAN and ISX,
                IP is greater than the effective number of observations.
      or
IFAIL = 4
      On entry, Y(i) < 0.0 for some i = 1, 2, ..., n.
```

IFAIL = 5

A fitted value is at the boundary, i.e., $\hat{\mu} = 0.0$. This may occur if there are y values of 0.0 and the model is too complex for the data. The model should be reformulated with, perhaps, some observations dropped.

```
IFAIL = 6
```

The singular value decomposition has failed to converge. This is an unlikely error exit.

IFAIL = 7

The iterative weighted least-squares has failed to converge in MAXIT (or default 10) iterations. The value of MAXIT could be increased but it may be advantageous to examine the convergence using the IPRINT option. This may indicate that the convergence is slow because the solution is at a boundary in which case it may be better to reformulate the model.

IFAIL = 8

The rank of the model has changed during the weighted least-squares iterations. The estimate for β returned may be reasonable, but the user should check how the deviance has changed during iterations.

IFAIL = 9

The degrees of freedom for error are 0. A saturated model has been fitted.

7 Accuracy

The accuracy depends on the value of TOL as described in Section 5. As the deviance is a function of $\log \mu$ the accuracy of the $\hat{\beta}$ will only be a function of TOL. TOL should therefore be set smaller than the accuracy required for $\hat{\beta}$.

8 Further Comments

None.

9 Example

A 3 by 5 contingency table given by Plackett (1974) is analysed by fitting terms for rows and columns. The table is:

```
141 67 114 79 39
131 66 143 72 35.
36 14 38 28 16
```

9.1 Program Text

Note: the listing of the example program presented below uses **bold italicised** terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
GO2GCF Example Program Text
*
      Mark 14 Release. NAG Copyright 1989.
      .. Parameters ..
                         NMAX, MMAX
      TNTEGER
      PARAMETER
                         (NMAX=15, MMAX=9)
                        NIN, NOUT
      INTEGER
      PARAMETER
                        (NIN=5,NOUT=6)
      .. Local Scalars ..
                        A, DEV, EPS, TOL
      INTEGER
                        I, IDF, IFAIL, IP, IPRINT, IRANK, J, M, MAXIT, N
      CHARACTER
                        LINK, MEAN, OFFSET, WEIGHT
      .. Local Arrays ..
                         B(MMAX), COV((MMAX*MMAX+MMAX)/2), SE(MMAX),
      real
                         V(NMAX, 7+MMAX), WK((MMAX*MMAX+3*MMAX+22)/2),
                         \mathtt{WT}(\mathtt{NMAX}), \mathtt{X}(\mathtt{NMAX},\mathtt{MMAX}), \mathtt{Y}(\mathtt{NMAX})
      INTEGER
                         ISX(MMAX)
      .. External Subroutines ..
                        G02GCF
      .. Executable Statements ..
      WRITE (NOUT,*) 'GO2GCF Example Program Results'
      Skip heading in data file
      READ (NIN, *)
      READ (NIN,*) LINK, MEAN, OFFSET, WEIGHT, N, M, IPRINT
      IF (N.LE.NMAX .AND. M.LT.MMAX) THEN
         IF (WEIGHT.EQ.'W' .OR. WEIGHT.EQ.'w') THEN
             DO 20 I = 1, N
                READ (NIN,*) (X(I,J),J=1,M), Y(I), WT(I)
   20
             CONTINUE
         ELSE
            DO 40 I = 1, N
                READ (NIN,*) (X(I,J),J=1,M), Y(I)
   40
            CONTINUE
         END IF
         READ (NIN, \star) (ISX(J), J=1, M)
         Calculate IP
         IP = 0
         DO 60 J = 1, M
```

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```
IF (ISX(J).GT.0) IP = IP + 1
   60
          CONTINUE
          IF (MEAN.EQ.'M' .OR. MEAN.EQ.'m') IP = IP + 1
IF (LINK.EQ.'E' .OR. LINK.EQ.'e') READ (NIN,*) A
          Set control parameters
          EPS = 0.000001e0
          TOL = 0.00005e0
          MAXIT = 10
          IFAIL = -1
          CALL GO2GCF(LINK, MEAN, OFFSET, WEIGHT, N, X, NMAX, M, ISX, IP, Y, WT, A,
     +
                       DEV, IDF, B, IRANK, SE, COV, V, NMAX, TOL, MAXIT, IPRINT, EPS,
                       WK, IFAIL)
          IF (IFAIL.EQ.O .OR. IFAIL.GE.7) THEN
             WRITE (NOUT,*)
             WRITE (NOUT, 99999) 'Deviance = ', DEV
             WRITE (NOUT, 99998) 'Degrees of freedom = ', IDF
             WRITE (NOUT, *)
             WRITE (NOUT, *) '
                                     Estimate
                                                    Standard error'
             WRITE (NOUT, *)
             DO 80 I = 1, IP
                WRITE (NOUT, 99997) B(I), SE(I)
   80
             CONTINUE
             WRITE (NOUT, *)
             WRITE (NOUT,*) '
                                   Y
                                             FV
                                                      Residual
             WRITE (NOUT, *)
             DO 100 I = 1, N
                WRITE (NOUT, 99996) Y(I), V(I,2), V(I,5), V(I,6)
  100
             CONTINUE
         END IF
      END IF
      STOP
99999 FORMAT (1X,A,e12.4)
99998 FORMAT (1X,A,I2)
99997 FORMAT (1X,2F14.4)
99996 FORMAT (1x,F7.1,F10.2,F12.4,F10.3)
      END
```

9.2 Program Data

```
GO2GCF Example Program Data
'L' 'M' 'N' 'U' 15 8 0
1.0 0.0 0.0 1.0 0.0 0.0 0.0 0.0 141.
1.0 0.0 0.0 0.0 1.0 0.0 0.0 0.0 67.
1.0 0.0 0.0 0.0 0.0 1.0 0.0 0.0 114.
1.0 0.0 0.0 0.0 0.0 0.0 1.0 0.0
1.0 0.0 0.0 0.0 0.0 0.0 0.0 1.0
0.0 1.0 0.0 1.0 0.0 0.0 0.0 0.0 131.
0.0 1.0 0.0 0.0 1.0 0.0 0.0 0.0 66.
0.0 1.0 0.0 0.0 0.0 1.0 0.0 0.0 143.
0.0 1.0 0.0 0.0 0.0 0.0 1.0 0.0
                                 72.
0.0 1.0 0.0 0.0 0.0 0.0 0.0 1.0
0.0 0.0 1.0 1.0 0.0 0.0 0.0 0.0
                                 36.
0.0 0.0 1.0 0.0 1.0 0.0 0.0 0.0
0.0 0.0 1.0 0.0 0.0 1.0 0.0 0.0
                                 38.
0.0 0.0 1.0 0.0 0.0 0.0 1.0 0.0
0.0 0.0 1.0 0.0 0.0 0.0 0.0 1.0
           1
                1
```

9.3 Program Results

GO2GCF Example Program Results

Deviance = 0.9038E+01 Degrees of freedom = 8

Est	timate	Standard err	or
2.5977 1.2619 1.2777 0.0580 1.0307 0.2910 0.9876 0.4880 -0.1996		0.0258 0.0438 0.0436 0.0668 0.0551 0.0732 0.0559 0.0675 0.0904	
Y	FV	Residual	Н
141.0 67.0 114.0 79.0 39.0 131.0 66.0 143.0 72.0 35.0 36.0 14.0 38.0 28.0	132.99 63.47 127.38 77.29 38.86 135.11 64.48 129.41 78.52 39.48 39.90 19.04 38.21 23.19 11.66	0.6875 0.4386 -1.2072 0.1936 0.0222 -0.3553 0.1881 1.1749 -0.7465 -0.7271 -0.6276 -1.2131 -0.0346 0.9675 1.2028	0.604 0.514 0.596 0.532 0.482 0.608 0.520 0.601 0.537 0.488 0.393 0.255 0.382 0.282

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