

# NAG Fortran Library Routine Document

## G01ZUF

**Note:** before using this routine, please read the Users' Note for your implementation to check the interpretation of ***bold italicised*** terms and other implementation-dependent details.

### 1 Purpose

G01ZUF is used to initialize routines G01MUF and G01EUF.

It is intended to be used before a call to G01MUF or G01EUF.

### 2 Specification

```
SUBROUTINE G01ZUF (RKAPPA, BETA2, MODE, XL, XU, WORK, IFAIL)
  INTEGER           MODE, IFAIL
  double precision RKAPPA, BETA2, XL, XU, WORK(322)
```

### 3 Description

G01ZUF initializes the array WORK for use by G01MUF or G01EUF in the evaluation of the Vavilov functions  $\phi_V(\lambda; \kappa, \beta^2)$  and  $\Phi_V(\lambda; \kappa, \beta^2)$  respectively.

### 4 References

Schorr B (1974) Programs for the Landau and the Vavilov distributions and the corresponding random numbers *Comp. Phys. Comm.* 7 215–224

### 5 Parameters

- |   |               |
|---|---------------|
| 1: RKAPPA – <b>double precision</b>   | <i>Input</i>  |
| <i>On entry:</i> the argument $\kappa$ of the function.   |               |
| <i>Constraint:</i> $0.01 \leq \text{RKAPPA} \leq 10.0$ .  |               |
| 2: BETA2 – <b>double precision</b>  | <i>Input</i>  |
| <i>On entry:</i> the argument $\beta^2$ of the function.  |               |
| <i>Constraint:</i> $0.0 \leq \text{BETA2} \leq 1.0$ .   |               |
| 3: MODE – INTEGER   | <i>Input</i>  |
| <i>On entry:</i> if $\text{MODE} = 0$ , then G01MUF is to be called after the call to G01ZUF. Otherwise, G01EUF is to be called.  |               |
| 4: XL – <b>double precision</b>   | <i>Output</i> |
| <i>On exit:</i> $x_l$ , a threshold value below which $\phi_V(\lambda; \kappa, \beta^2)$ will be set to zero by G01MUF and $\Phi_V(\lambda; \kappa, \beta^2)$ will be set to zero by G01EUF if $\lambda > x_l$ .  |               |
| 5: XU – <b>double precision</b>   | <i>Output</i> |
| <i>On exit:</i> $x_u$ , a threshold value above which $\phi_V(\lambda; \kappa, \beta^2)$ will be set to zero by G01MUF and $\Phi_V(\lambda; \kappa, \beta^2)$ will be set to unity by G01EUF if $\lambda > x_u$ . |               |

6: WORK(322) – *double precision* array *Communication Array*

*On exit:* this parameter should be passed unchanged to G01EUF or G01MUF.

7: IFAIL – INTEGER *Input/Output*

*On entry:* IFAIL must be set to 0, -1 or 1. Users who are unfamiliar with this parameter should refer to Chapter P01 for details.

*On exit:* IFAIL = 0 unless the routine detects an error (see Section 6).

For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, for users not familiar with this parameter the recommended value is 0. **When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.**

## 6 Error Indicators and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

IFAIL = 1

On entry, RKAPPA < 0.01,  
or           RKAPPA > 10.0,  
or           BETA2 < 0.0,  
or           BETA2 > 1.0.

IFAIL = 2

The initialization has been abandoned due to an internal error. This error exit is unlikely to occur, but if it does change the values of RKAPPA and/or BETA2 and rerun G01ZUF.

## 7 Accuracy

At least 5 significant digits are usually correct.

## 8 Further Comments

None.

## 9 Example

See Section 9 of the documents for G01MUF and G01EUF.

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