

NAG Fortran Library Routine Document

F08UEF (SSBGST/DSBGST)

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of ***bold italicised*** terms and other implementation-dependent details.

1 Purpose

F08UEF (SSBGST/DSBGST) reduces a real symmetric-definite generalized eigenproblem $Az = \lambda Bz$ to the standard form $Cy = \lambda y$, where A and B are band matrices, A is a real symmetric matrix, and B has been factorized by F08UFF (SPBSTF/DPBSTF).

2 Specification

```

SUBROUTINE F08UEF(VECT, UPLO, N, KA, KB, AB, LDAB, BB, LDBB, X, LDX,
1              WORK, INFO)
ENTRY          ssbgst (VECT, UPLO, N, KA, KB, AB, LDAB, BB, LDBB, X, LDX,
1              WORK, INFO)
INTEGER        N, KA, KB, LDAB, LDBB, LDX, INFO
real          AB(LDAB,*), BB(LDBB,*), X(LDX,*), WORK(*)
CHARACTER*1    VECT, UPLO

```

The ENTRY statement enables the routine to be called by its LAPACK name.

3 Description

To reduce the real symmetric-definite generalized eigenproblem $Az = \lambda Bz$ to the standard form $Cy = \lambda y$, where A , B and C are banded, this routine must be preceded by a call to F08UFF (SPBSTF/DPBSTF) which computes the split Cholesky factorization of the positive-definite matrix B : $B = S^T S$. The split Cholesky factorization, compared with the ordinary Cholesky factorization, allows the work to be approximately halved.

This routine overwrites A with $C = X^T A X$, where $X = S^{-1} Q$ and Q is a orthogonal matrix chosen (implicitly) to preserve the bandwidth of A . The routine also has an option to allow the accumulation of X , and then, if z is an eigenvector of C , Xz is an eigenvector of the original system.

4 References

Crawford C R (1973) Reduction of a band-symmetric generalized eigenvalue problem *Comm. ACM* **16** 41–44

Kaufman L (1984) Banded eigenvalue solvers on vector machines *ACM Trans. Math. Software* **10** 73–86

5 Parameters

1: VECT – CHARACTER*1 *Input*

On entry: indicates whether X is to be returned as follows:

if VECT = 'N', X is not returned;

if VECT = 'V', X is returned.

Constraint: VECT = 'N' or 'V'.

- 2: UPLO – CHARACTER*1 *Input*
On entry: indicates whether the upper or lower triangular part of A is stored as follows:
 if UPLO = 'U', the upper triangular part of A is stored;
 if UPLO = 'L', the lower triangular part of A is stored.
Constraint: UPLO = 'U' or 'L'.
- 3: N – INTEGER *Input*
On entry: n , the order of the matrices A and B .
Constraint: $N \geq 0$.
- 4: KA – INTEGER *Input*
On entry: k_A , the number of super-diagonals of the matrix A if UPLO = 'U', or the number of sub-diagonals if UPLO = 'L'.
Constraint: $KA \geq 0$.
- 5: KB – INTEGER *Input*
On entry: k_B , the number of super-diagonals of the matrix B if UPLO = 'U', or the number of sub-diagonals if UPLO = 'L'.
Constraint: $KA \geq KB \geq 0$.
- 6: AB(LDAB,*) – **real** array *Input/Output*
Note: the second dimension of the array AB must be at least $\max(1, N)$.
On entry: the n by n symmetric band matrix A , stored in rows 1 to $k_A + 1$. More precisely, if UPLO = 'U', the elements of the upper triangle of A within the band must be stored with element a_{ij} in $AB(k_A + 1 + i - j, j)$ for $\max(1, j - k_A) \leq i \leq j$; if UPLO = 'L', the elements of the lower triangle of A within the band must be stored with element a_{ij} in $AB(1 + i - j, j)$ for $j \leq i \leq \min(n, j + k_A)$.
On exit: the upper or lower triangle of A is overwritten by the corresponding upper or lower triangle of C as specified by UPLO.
- 7: LDAB – INTEGER *Input*
On entry: the first dimension of the array AB as declared in the (sub)program from which F08UEF (SSBGST/DSBGST) is called.
Constraint: $LDAB \geq KA + 1$.
- 8: BB(LDBB,*) – **real** array *Input*
Note: the second dimension of the array BB must be at least $\max(1, N)$.
On entry: the banded split Cholesky factor of B as specified by UPLO, N and KB and returned by F08UFF (SPBSTF/DPBSTF).
- 9: LDBB – INTEGER *Input*
On entry: the first dimension of the array BB as declared in the (sub)program from which F08UEF (SSBGST/DSBGST) is called.
Constraint: $LDBB \geq KB + 1$.

- 10: $X(LDX,*)$ – *real* array *Output*
Note: the second dimension of the array X must be at least $\max(1, N)$ if $VECT = 'V'$, and at least 1 if $VECT = 'N'$.
On exit: the n by n matrix $X = S^{-1}Q$, if $VECT = 'V'$.
 X is not referenced if $VECT = 'N'$.
- 11: LDX – INTEGER *Input*
On entry: the first dimension of the array X as declared in the (sub)program from which F08UEF (SSBGST/DSBGST) is called.
Constraints:
 $LDX \geq \max(1, N)$ if $VECT = 'V'$,
 $LDX \geq 1$ if $VECT = 'N'$.
- 12: $WORK(*)$ – *real* array *Workspace*
Note: the dimension of the array $WORK$ must be at least $\max(1, 2 * N)$.
- 13: $INFO$ – INTEGER *Output*
On exit: $INFO = 0$ unless the routine detects an error (see Section 6).

6 Error Indicators and Warnings

$INFO < 0$

If $INFO = -i$, the i th parameter had an illegal value. An explanatory message is output, and execution of the program is terminated.

7 Accuracy

Forming the reduced matrix C is a stable procedure. However it involves implicit multiplication by B^{-1} . When the routine is used as a step in the computation of eigenvalues and eigenvectors of the original problem, there may be a significant loss of accuracy if B is ill-conditioned with respect to inversion.

8 Further Comments

The total number of floating-point operations is approximately $6n^2k_B$, when $VECT = 'N'$, assuming $n \gg k_A, k_B$; there are an additional $(3/2)n^3(k_B/k_A)$ operations when $VECT = 'V'$.

The complex analogue of this routine is F08USF (CHBGST/ZHBGST).

9 Example

To compute all the eigenvalues of $Az = \lambda Bz$, where

$$A = \begin{pmatrix} 0.24 & 0.39 & 0.42 & 0.00 \\ 0.39 & -0.11 & 0.79 & 0.63 \\ 0.42 & 0.79 & -0.25 & 0.48 \\ 0.00 & 0.63 & 0.48 & -0.03 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 2.07 & 0.95 & 0.00 & 0.00 \\ 0.95 & 1.69 & -0.29 & 0.00 \\ 0.00 & -0.29 & 0.65 & -0.33 \\ 0.00 & 0.00 & -0.33 & 1.17 \end{pmatrix}.$$

Here A is symmetric, B is symmetric positive-definite, and A and B are treated as band matrices. B must first be factorized by F08UFF (SPBSTF/DPBSTF). The program calls F08UEF (SSBGST/DSBGST) to reduce the problem to the standard form $Cy = \lambda y$, then F08HEF (SSBTRD/DSBTRD) to reduce C to tridiagonal form, and F08JFF (SSTERF/DSTERF) to compute the eigenvalues.

9.1 Program Text

Note: the listing of the example program presented below uses *bold italicised* terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```

*      F08UEF Example Program Text.
*      Mark 19 Release. NAG Copyright 1999.
*      .. Parameters ..
INTEGER          NIN, NOUT
PARAMETER        (NIN=5,NOUT=6)
INTEGER          NMAX, KMAX, LDAB, LDBB, LDX
PARAMETER        (NMAX=8,KMAX=8,LDAB=KMAX-1,LDBB=KMAX-1,LDX=NMAX)
*      .. Local Scalars ..
INTEGER          I, INFO, J, KA, KB, N
CHARACTER        UPLO
*      .. Local Arrays ..
real            AB(LDAB,NMAX), BB(LDBB,NMAX), D(NMAX), E(NMAX-1),
+                WORK(2*NMAX), X(LDX,NMAX)
*      .. External Subroutines ..
EXTERNAL         spbstf, ssbgst, ssbtrd, ssterf
*      .. Intrinsic Functions ..
INTRINSIC        MAX, MIN
*      .. Executable Statements ..
WRITE (NOUT,*) 'F08UEF Example Program Results'
*      Skip heading in data file
READ (NIN,*)
READ (NIN,*) N, KA, KB
IF (N.LE.NMAX .AND. KA.LE.KMAX .AND. KB.LE.KA) THEN
*
*      Read A and B from data file
*
      READ (NIN,*) UPLO
      IF (UPLO.EQ.'U') THEN
        DO 20 I = 1, N
          READ (NIN,*) (AB(KA+1+I-J,J),J=I,MIN(N,I+KA))
20      CONTINUE
        DO 40 I = 1, N
          READ (NIN,*) (BB(KB+1+I-J,J),J=I,MIN(N,I+KB))
40      CONTINUE
      ELSE IF (UPLO.EQ.'L') THEN
        DO 60 I = 1, N
          READ (NIN,*) (AB(1+I-J,J),J=MAX(1,I-KA),I)
60      CONTINUE
        DO 80 I = 1, N
          READ (NIN,*) (BB(1+I-J,J),J=MAX(1,I-KB),I)
80      CONTINUE
      END IF
*
*      Compute the split Cholesky factorization of B
*
      CALL spbstf(UPLO,N,KB,BB,LDBB,INFO)
*
      WRITE (NOUT,*)
      IF (INFO.GT.0) THEN
        WRITE (NOUT,*) 'B is not positive-definite.'
      ELSE
*
*      Reduce the problem to standard form C*y = lambda*y, storing
*      the result in A
*
        CALL ssbgst('N',UPLO,N,KA,KB,AB,LDAB,BB,LDBB,X,LDX,WORK,
+                INFO)
*
*      Reduce C to tridiagonal form T = (Q**T)*C*Q
*
        CALL ssbtrd('N',UPLO,N,KA,AB,LDAB,D,E,X,LDX,WORK,INFO)
*
*      Calculate the eigenvalues of T (same as C)
*
        CALL ssterf(N,D,E,INFO)

```

```

*
      IF (INFO.GT.0) THEN
        WRITE (NOUT,*) 'Failure to converge.'
      ELSE
*
        Print eigenvalues
*
        WRITE (NOUT,*) 'Eigenvalues'
        WRITE (NOUT,99999) (D(I),I=1,N)
      END IF
    END IF
  END IF
  STOP
*
99999 FORMAT (3X,(8F8.4))
END

```

9.2 Program Data

F08UEF Example Program Data

4	2	1			:Values of N, KA and KB
'L'					:Value of UPLO
0.24					
0.39	-0.11				
0.42	0.79	-0.25			
	0.63	0.48	-0.03		:End of matrix A
2.07					
0.95	1.69				
	-0.29	0.65			
		-0.33	1.17		:End of matrix B

9.3 Program Results

F08UEF Example Program Results

Eigenvalues
 -0.8305 -0.6401 0.0992 1.8525
