NAG Fortran Library Routine Document F08QVF (CTRSYL/ZTRSYL)

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of **bold italicised** terms and other implementation-dependent details.

1 Purpose

F08QVF (CTRSYL/ZTRSYL) solves the complex triangular Sylvester matrix equation.

2 Specification

```
SUBROUTINE FO8QVF(TRANA, TRANB, ISGN, M, N, A, LDA, B, LDB, C, LDC, SCALE, INFO)

ENTRY ctrsyl (TRANA, TRANB, ISGN, M, N, A, LDA, B, LDB, C, LDC, SCALE, INFO)

INTEGER ISGN, M, N, LDA, LDB, LDC, INFO real SCALE A(LDA,*), B(LDB,*), C(LDC,*)

CHARACTER*1 TRANA, TRANB
```

The ENTRY statement enables the routine to be called by its LAPACK name.

3 Description

This routine solves the complex Sylvester matrix equation

$$op(A)X \pm Xop(B) = \alpha C$$
,

where op(A) = A or A^H , and the matrices A and B are upper triangular; α is a scale factor (≤ 1) determined by the routine to avoid overflow in X; A is m by m and B is n by n while the right-hand side matrix C and the solution matrix X are both m by n. The matrix X is obtained by a straightforward process of back substitution (see Golub and van Loan (1996)).

Note that the equation has a unique solution if and only if $\alpha_i \pm \beta_i \neq 0$, where $\{\alpha_i\}$ and $\{\beta_i\}$ are the eigenvalues of A and B respectively and the sign (+ or -) is the same as that used in the equation to be solved.

4 References

Golub G H and van Loan C F (1996) Matrix Computations (3rd Edition) Johns Hopkins University Press, Baltimore

Higham N J (1992) Perturbation theory and backward error for AX - XB = C Numerical Analysis Report University of Manchester

5 Parameters

1: TRANA – CHARACTER*1

Input

On entry: specifies the option op(A) as follows:

if TRANA = 'N', then
$$op(A) = A$$
;
if TRANA = 'C', then $op(A) = A^H$.

Constraint: TRANA = 'N' or 'C'.

2: TRANB - CHARACTER*1

Input

On entry: specifies the option op(B) as follows:

if TRANB = 'N', then
$$op(B) = B$$
;

if TRANB = 'C', then
$$op(B) = B^H$$
.

Constraint: TRANB = 'N' or 'C'.

3: ISGN – INTEGER

Input

On entry: indicates the form of the Sylvester equation as follows:

if ISGN = +1, then the equation is of the form
$$op(A)X + X op(B) = \alpha C$$
;

if ISGN = -1, then the equation is of the form
$$op(A)X - X op(B) = \alpha C$$
.

Constraint: ISGN = ± 1 .

4: M - INTEGER

Input

On entry: m, the order of the matrix A, and the number of rows in the matrices X and C.

Constraint: $M \ge 0$.

5: N – INTEGER

Input

On entry: n, the order of the matrix B, and the number of columns in the matrices X and C.

Constraint: $N \ge 0$.

6: A(LDA,*) - complex array

Input

Note: the second dimension of the array A must be at least max(1, M).

On entry: the m by m upper triangular matrix A.

7: LDA – INTEGER

Input

On entry: the first dimension of the array A as declared in the (sub)program from which F08QVF (CTRSYL/ZTRSYL) is called.

Constraint: LDA $\geq \max(1, M)$.

8: B(LDB,*) - complex array

Input

Note: the second dimension of the array B must be at least max(1, N).

On entry: the n by n upper triangular matrix B.

9: LDB – INTEGER

Input

On entry: the first dimension of the array B as declared in the (sub)program from which F08QVF (CTRSYL/ZTRSYL) is called.

Constraint: LDB $\geq \max(1, N)$.

10: C(LDC,*) - complex array

Input/Output

Note: the second dimension of the array C must be at least max(1, N).

On entry: the m by n right-hand side matrix C.

On exit: C is overwritten by the solution matrix X.

11: LDC – INTEGER Input

On entry: the first dimension of the array C as declared in the (sub)program from which F08QVF (CTRSYL/ZTRSYL) is called.

Constraint: LDC $\geq \max(1, M)$.

12: SCALE – real Output

On exit: the value of the scale factor α .

13: INFO – INTEGER Output

On exit: INFO = 0 unless the routine detects an error (see Section 6).

6 Error Indicators and Warnings

INFO < 0

If INFO = -i, the *i*th parameter had an illegal value. An explanatory message is output, and execution of the program is terminated.

INFO = 1

A and B have common or close eigenvalues, perturbed values of which were used to solve the equation.

7 Accuracy

Consider the equation AX - XB = C. (To apply the remarks to the equation AX + XB = C, simply replace B by -B.)

Let \tilde{X} be the computed solution and R the residual matrix:

$$R = C - (A\tilde{X} - \tilde{X}B).$$

Then the residual is always small:

$$||R||_F = O(\epsilon) (||A||_F + ||B||_F) ||\tilde{X}||_F.$$

However, \tilde{X} is **not** necessarily the exact solution of a slightly perturbed equation; in other words, the solution is not backwards stable.

For the forward error, the following bound holds:

$$\|\tilde{X} - X\|_F \le \frac{\|R\|_F}{sep(A, B)}$$

but this may be a considerable overestimate. See Golub and van Loan (1996) for a definition of sep(A,B), and Higham (1992) for further details.

These remarks also apply to the solution of a general Sylvester equation, as described in Section 8.

8 Further Comments

The total number of real floating-point operations is approximately 4mn(m+n).

To solve the general complex Sylvester equation

$$AX \pm XB = C$$

where A and B are general matrices, A and B must first be reduced to Schur form (by calling F02GAF, for example):

$$A = Q_1 \tilde{A} Q_1^H$$
 and $B = Q_2 \tilde{B} Q_2^H$

where \tilde{A} and \tilde{B} are upper triangular and Q_1 and Q_2 are unitary. The original equation may then be transformed to:

$$\tilde{A}\tilde{X} \pm \tilde{X}\tilde{B} = \tilde{C}$$

where $\tilde{X}=Q_1^HXQ_2$ and $\tilde{C}=Q_1^HCQ_2$. \tilde{C} may be computed by matrix multiplication; F08QVF (CTRSYL/ZTRSYL) may be used to solve the transformed equation; and the solution to the original equation can be obtained as $X = Q_1 \tilde{X} Q_2^H$.

The real analogue of this routine is F08QHF (STRSYL/DTRSYL).

Example

To solve the Sylvester equation AX + XB = C, where

$$A = \begin{pmatrix} -6.00 - 7.00i & 0.36 - 0.36i & -0.19 + 0.48i & 0.88 - 0.25i \\ 0.00 + 0.00i & -5.00 + 2.00i & -0.03 - 0.72i & -0.23 + 0.13i \\ 0.00 + 0.00i & 0.00 + 0.00i & 8.00 - 1.00i & 0.94 + 0.53i \\ 0.00 + 0.00i & 0.00 + 0.00i & 0.00 + 0.00i & 3.00 - 4.00i \end{pmatrix}$$

$$B = \begin{pmatrix} 0.50 - 0.20i & -0.29 - 0.16i & -0.37 + 0.84i & -0.55 + 0.73i \\ 0.00 + 0.00i & -0.40 + 0.90i & 0.06 + 0.22i & -0.43 + 0.17i \\ 0.00 + 0.00i & 0.00 + 0.00i & -0.90 - 0.10i & -0.89 - 0.42i \\ 0.00 + 0.00i & 0.00 + 0.00i & 0.00 + 0.00i & 0.30 - 0.70i \end{pmatrix}$$

$$B = \begin{pmatrix} 0.50 - 0.20i & -0.29 - 0.16i & -0.37 + 0.84i & -0.55 + 0.73i \\ 0.00 + 0.00i & -0.40 + 0.90i & 0.06 + 0.22i & -0.43 + 0.17i \\ 0.00 + 0.00i & 0.00 + 0.00i & -0.90 - 0.10i & -0.89 - 0.42i \\ 0.00 + 0.00i & 0.00 + 0.00i & 0.00 + 0.00i & 0.30 - 0.70i \end{pmatrix}$$

and

$$C = \begin{pmatrix} 0.63 + 0.35i & 0.45 - 0.56i & 0.08 - 0.14i & -0.17 - 0.23i \\ -0.17 + 0.09i & -0.07 - 0.31i & 0.27 - 0.54i & 0.35 + 1.21i \\ -0.93 - 0.44i & -0.33 - 0.35i & 0.41 - 0.03i & 0.57 + 0.84i \\ 0.54 + 0.25i & -0.62 - 0.05i & -0.52 - 0.13i & 0.11 - 0.08i \end{pmatrix}$$

9.1 **Program Text**

Note: the listing of the example program presented below uses bold italicised terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
F08QVF Example Program Text
Mark 16 Release. NAG Copyright 1992.
.. Parameters ..
INTEGER NIN, NOUT
                (NIN=5,NOUT=6)
MMAX, NMAX, LDA, LDB, LDC
PARAMETER
INTEGER MMAX, NMAX, LDA, LDB, LDC
PARAMETER (MMAX=8,NMAX=8,LDA=MMAX,LDB=NMAX,LDC=MMAX)
.. Local Scalars ..
       SCALE
real
INTEGER
                  I, IFAIL, INFO, J, M, N
.. Local Arrays ..
complex
CHARACTER
A(LDA,MMAX), B(LDB,NMAX), C(LDC,NMAX)
CLABS(1), RLABS(1)
.. External Subroutines ..
EXTERNAL X04DBF, ctrsyl
.. Executable Statements ..
WRITE (NOUT,*) 'F08QVF Example Program Results'
Skip heading in data file
READ (NIN, *)
READ (NIN,*) M, N
IF (M.LE.MMAX .AND. N.LE.NMAX) THEN
   Read A, B and C from data file
   READ (NIN,*) ((A(I,J),J=1,M),I=1,M)
   READ (NIN,*) ((B(I,J),J=1,N),I=1,N)
   READ (NIN, *) ((C(I, J), J=1, N), I=1, M)
```

9.2 Program Data

```
FO8QVF Example Program Data
                                                                    :Values of M and N
 4 4
 (-6.00, -7.00) (0.36, -0.36) (-0.19, 0.48) (0.88, -0.25)
 ( 0.00, 0.00) (-5.00, 2.00) (-0.03,-0.72) (-0.23, 0.13)
 (0.00, 0.00) (0.00, 0.00) (8.00,-1.00) (0.94, 0.53) (0.00, 0.00) (0.00, 0.00) (0.00, 0.00) (3.00,-4.00)
                                                                     :End of matrix A
 (0.50,-0.20) (-0.29,-0.16) (-0.37, 0.84) (-0.55, 0.73)
 (0.00, 0.00) (-0.40, 0.90) (0.06, 0.22) (-0.43, 0.17)
 ( 0.00, 0.00) ( 0.00, 0.00) (-0.90,-0.10) (-0.89,-0.42) ( 0.00, 0.00) ( 0.00, 0.00) ( 0.00, 0.00) ( 0.30,-0.70)
                                                                     :End of matrix B
 ( 0.63, 0.35) ( 0.45,-0.56) ( 0.08,-0.14) (-0.17,-0.23)
 (-0.17, 0.09) (-0.07,-0.31) ( 0.27,-0.54) ( 0.35, 1.21)
 (-0.93, -0.44) (-0.33, -0.35) (0.41, -0.03) (0.57, 0.84)
 (0.54, 0.25) (-0.62, -0.05) (-0.52, -0.13) (0.11, -0.08)
                                                                   :End of matrix C
```

9.3 Program Results

```
F08QVF Example Program Results
```