NAG Fortran Library Routine Document F08FUF (CUNMTR/ZUNMTR)

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of **bold italicised** terms and other implementation-dependent details.

1 Purpose

F08FUF (CUNMTR/ZUNMTR) multiplies an arbitrary complex matrix C by the complex unitary matrix Q which was determined by F08FSF (CHETRD/ZHETRD) when reducing a complex Hermitian matrix to tridiagonal form.

2 Specification

```
SUBROUTINE FO8FUF(SIDE, UPLO, TRANS, M, N, A, LDA, TAU, C, LDC, WORK, LWORK, INFO)

ENTRY cunmtr (SIDE, UPLO, TRANS, M, N, A, LDA, TAU, C, LDC, WORK, LWORK, INFO)

INTEGER M, N, LDA, LDC, LWORK, INFO A(LDA,*), TAU(*), C(LDC,*), WORK(*)

CHARACTER*1 SIDE, UPLO, TRANS
```

The ENTRY statement enables the routine to be called by its LAPACK name.

3 Description

This routine is intended to be used after a call to F08FSF (CHETRD/ZHETRD), which reduces a complex Hermitian matrix A to real symmetric tridiagonal form T by a unitary similarity transformation: $A = QTQ^H$. F08FSF represents the unitary matrix Q as a product of elementary reflectors.

This routine may be used to form one of the matrix products

$$QC, Q^HC, CQ \text{ or } CQ^H$$

overwriting the result on C (which may be any complex rectangular matrix).

A common application of this routine is to transform a matrix Z of eigenvectors of T to the matrix QZ of eigenvectors of A.

4 References

Golub G H and van Loan C F (1996) Matrix Computations (3rd Edition) Johns Hopkins University Press, Baltimore

5 Parameters

Input

On entry: indicates how Q or Q^H is to be applied to C as follows:

if SIDE = 'L',
$$Q$$
 or Q^H is applied to C from the left;

if SIDE = 'R',
$$Q$$
 or Q^H is applied to C from the right.

Constraint: SIDE = 'L' or 'R'.

2: UPLO – CHARACTER*1

Input

On entry: this **must** be the same parameter UPLO as supplied to F08FSF (CHETRD/ZHETRD). Constraint: UPLO = 'U' or 'L'.

3: TRANS - CHARACTER*1

Input

On entry: indicates whether Q or Q^H is to be applied to C as follows:

if TRANS = 'N', Q is applied to C;

if TRANS = 'C', Q^H is applied to C.

Constraint: TRANS = 'N' or 'C'.

4: M - INTEGER

Input

On entry: m, the number of rows of the matrix C; m is also the order of Q if SIDE = 'L'.

Constraint: $M \ge 0$.

5: N – INTEGER

Input

On entry: n, the number of columns of the matrix C; n is also the order of Q if SIDE = 'R'.

Constraint: $N \ge 0$.

6: A(LDA,*) - complex array

Input/Output

Note: the second dimension of the array A must be at least max(1, M) if SIDE = L' and at least max(1, N) if SIDE = R'.

On entry: details of the vectors which define the elementary reflectors, as returned by F08FSF (CHETRD/ZHETRD).

On exit: used as internal workspace prior to being restored and hence is unchanged.

7: LDA – INTEGER

Input

On entry: the first dimension of the array A as declared in the (sub)program from which F08FUF (CUNMTR/ZUNMTR) is called.

Constraints:

LDA $\geq \max(1, M)$ if SIDE = 'L', LDA $\geq \max(1, N)$ if SIDE = 'R'.

8: TAU(*) - complex array

Input

Note: the dimension of the array TAU must be at least max(1, M-1) if SIDE = L' and at least max(1, N-1) if SIDE = R'.

On entry: further details of the elementary reflectors, as returned by F08FSF (CHETRD/ZHETRD).

9: C(LDC,*) - complex array

Input/Output

Note: the second dimension of the array C must be at least max(1, N).

On entry: the m by n matrix C.

On exit: C is overwritten by QC or Q^HC or CQ or CQ^H as specified by SIDE and TRANS.

10: LDC - INTEGER

Input

On entry: the first dimension of the array C as declared in the (sub)program from which F08FUF (CUNMTR/ZUNMTR) is called.

Constraint: LDC $\geq \max(1, M)$.

11: WORK(*) - complex array

Workspace

Note: the dimension of the array WORK must be at least max(1, LWORK).

On exit: if INFO = 0, the real part of WORK(1) contains the minimum value of LWORK required for optimum performance.

12: LWORK – INTEGER

Input

On entry: the dimension of the array WORK as declared in the (sub)program from which F08FUF (CUNMTR/ZUNMTR) is called, unless LWORK = -1, in which case a workspace query is assumed and the routine only calculates the optimal dimension of WORK (using the formula given below).

Suggested value: for optimum performance LWORK should be at least $N \times nb$ if SIDE = 'L' and at least $M \times nb$ if SIDE = 'R', where nb is the **blocksize**.

Constraints:

LWORK
$$\geq \max(1, N)$$
 or LWORK $= -1$ if SIDE $=$ 'L', LWORK $\geq \max(1, M)$ or LWORK $= -1$ if SIDE $=$ 'R'.

13: INFO – INTEGER

Output

On exit: INFO = 0 unless the routine detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the routine:

INFO < 0

If INFO = -i, the *i*th parameter had an illegal value. An explanatory message is output, and execution of the program is terminated.

7 Accuracy

The computed result differs from the exact result by a matrix E such that

$$||E||_2 = O(\epsilon)||C||_2,$$

where ϵ is the *machine precision*.

8 Further Comments

The total number of real floating-point operations is approximately $8m^2n$ if SIDE = 'L' and $8mn^2$ if SIDE = 'R'.

The real analogue of this routine is F08FGF (SORMTR/DORMTR).

9 Example

To compute the two smallest eigenvalues, and the associated eigenvectors, of the matrix A, where

$$A = \begin{pmatrix} -2.28 + 0.00i & 1.78 - 2.03i & 2.26 + 0.10i & -0.12 + 2.53i \\ 1.78 + 2.03i & -1.12 + 0.00i & 0.01 + 0.43i & -1.07 + 0.86i \\ 2.26 - 0.10i & 0.01 - 0.43i & -0.37 + 0.00i & 2.31 - 0.92i \\ -0.12 - 2.53i & -1.07 - 0.86i & 2.31 + 0.92i & -0.73 + 0.00i \end{pmatrix}.$$

Here A is Hermitian and must first be reduced to tridiagonal form T by F08FSF (CHETRD/ZHETRD). The program then calls F08JJF (SSTEBZ/DSTEBZ) to compute the requested eigenvalues and F08JXF (CSTEIN/ZSTEIN) to compute the associated eigenvectors of T. Finally F08FUF (CUNMTR/ZUNMTR) is called to transform the eigenvectors to those of A.

9.1 Program Text

Note: the listing of the example program presented below uses **bold italicised** terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
FO8FUF Example Program Text
Mark 16 Release. NAG Copyright 1992.
.. Parameters ..
INTEGER
                 NIN, NOUT
PARAMETER
                 (NIN=5, NOUT=6)
INTEGER
                 NMAX, LDA, LDZ, LWORK
                 (NMAX=8,LDA=NMAX,LDZ=NMAX,LWORK=64*NMAX)
PARAMETER
real
                  ZERO
PARAMETER
                 (ZERO=0.0e0)
.. Local Scalars ..
real
                 VL, VU
INTEGER
                 I, IFAIL, INFO, J, M, N, NSPLIT
CHARACTER
                 UPLO
.. Local Arrays ..
complex
                 A(LDA, NMAX), TAU(NMAX), WORK(LWORK), Z(LDZ, NMAX)
real
                 D(NMAX), E(NMAX), RWORK(5*NMAX), W(NMAX)
INTEGER
                 IBLOCK(NMAX), IFAILV(NMAX), ISPLIT(NMAX),
                 IWORK (NMAX)
CHARACTER
                 CLABS(1), RLABS(1)
.. External Subroutines .
EXTERNAL
                 sstebz, XO4DBF, chetrd, cstein, cunmtr
.. Executable Statements ..
WRITE (NOUT,*) 'F08FUF Example Program Results'
Skip heading in data file
READ (NIN, *)
READ (NIN,*) N
IF (N.LE.NMAX) THEN
   Read A from data file
   READ (NIN, *) UPLO
   IF (UPLO.EQ.'U') THEN
      READ (NIN,*) ((A(I,J),J=I,N),I=1,N)
   ELSE IF (UPLO.EQ.'L') THEN
      READ (NIN,*) ((A(I,J),J=1,I),I=1,N)
   END IF
   Reduce A to tridiagonal form T = (Q**H)*A*Q
   CALL chetrd(UPLO,N,A,LDA,D,E,TAU,WORK,LWORK,INFO)
   Calculate the two smallest eigenvalues of T (same as A)
   CALL sstebz('I','B',N,VL,VU,1,2,ZERO,D,E,M,NSPLIT,W,IBLOCK,
               ISPLIT,RWORK,IWORK,INFO)
   WRITE (NOUT, *)
      (INFO.GT.O) THEN
      WRITE (NOUT,*) 'Failure to converge.'
      WRITE (NOUT, *) 'Eigenvalues'
      WRITE (NOUT, 99999) (W(I), I=1, M)
      Calculate the eigenvectors of T, storing the result in Z
      CALL cstein (N,D,E,M,W,IBLOCK,ISPLIT,Z,LDZ,RWORK,IWORK,
                  IFAILV, INFO)
      IF (INFO.GT.O) THEN
         WRITE (NOUT,*) 'Failure to converge.'
         Calculate the eigenvectors of A = Q * (eigenvectors of T)
         CALL cunmtr('Left', UPLO, 'No transpose', N, M, A, LDA, TAU, Z,
```

9.2 Program Data

```
FO8FUF Example Program Data

4
'L'
(-2.28, 0.00)
(1.78, 2.03) (-1.12, 0.00)
(2.26,-0.10) (0.01,-0.43) (-0.37, 0.00)
(-0.12,-2.53) (-1.07,-0.86) (2.31, 0.92) (-0.73, 0.00)
:End of matrix A
```

9.3 Program Results