NAG Fortran Library Routine Document

F07HHF (SPBRFS/DPBRFS)

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of *bold italicised* terms and other implementation-dependent details.

1 Purpose

F07HHF (SPBRFS/DPBRFS) returns error bounds for the solution of a real symmetric positive-definite band system of linear equations with multiple right-hand sides, AX = B. It improves the solution by iterative refinement, in order to reduce the backward error as much as possible.

2 Specification

```
SUBROUTINE F07HHF(UPLO, N, KD, NRHS, AB, LDAB, AFB, LDAFB, B, LDB, X,1LDX, FERR, BERR, WORK, IWORK, INFO)ENTRYspbrfs(UPLO, N, KD, NRHS, AB, LDAB, AFB, LDAFB, B, LDB, X,1LDX, FERR, BERR, WORK, IWORK, INFO)INTEGERN, KD, NRHS, LDAB, LDAFB, LDB, LDX, IWORK(*), INFOrealAB(LDAB,*), AFB(LDAFB,*), B(LDB,*), X(LDX,*), FERR(*),1BERR(*), WORK(*)UPLOUPLO
```

The ENTRY statement enables the routine to be called by its LAPACK name.

3 Description

This routine returns the backward errors and estimated bounds on the forward errors for the solution of a real symmetric positive-definite band system of linear equations with multiple right-hand sides AX = B. The routine handles each right-hand side vector (stored as a column of the matrix B) independently, so we describe the function of the routine in terms of a single right-hand side b and solution x.

Given a computed solution x, the routine computes the *component-wise backward error* β . This is the size of the smallest relative perturbation in each element of A and b such that x is the exact solution of a perturbed system

$$(A + \delta A)x = b + \delta b$$

 $|\delta a_{ij}| \le \beta |a_{ij}|$ and $|\delta b_i| \le \beta |b_i|.$

Then the routine estimates a bound for the *component-wise forward error* in the computed solution, defined by:

$$\max_{i} |x_i - \hat{x}_i| / \max_{i} |x_i|$$

where \hat{x} is the true solution.

For details of the method, the F07 Chapter Introduction.

4 References

Golub G H and van Loan C F (1996) Matrix Computations (3rd Edition) Johns Hopkins University Press, Baltimore

5 Parameters

J	
1:	UPLO – CHARACTER*1 Input
	On entry: indicates whether the upper or lower triangular part of A is stored and how A has been factorized, as follows:
	if UPLO = 'U', the upper triangular part of A is stored and A is factorized as $U^T U$, where U is upper triangular;
	if UPLO = 'L', the lower triangular part of A is stored and A is factorized as LL^T , where L is lower triangular.
	Constraint: $UPLO = 'U'$ or 'L'.
2:	N – INTEGER Input
	On entry: n, the order of the matrix A.
	Constraint: $N \ge 0$.
3:	KD – INTEGER Input
	On entry: k, the number of super-diagonals or sub-diagonals of the matrix A.
	Constraint: $KD \ge 0$.
4:	NRHS – INTEGER Input
	On entry: r, the number of right-hand sides.
	Constraint: NRHS ≥ 0 .
5:	AB(LDAB,*) – <i>real</i> array Input
	Note: the second dimension of the array AB must be at least $max(1, N)$.
	On entry: the n by n original symmetric band matrix A as supplied to F07HDF (SPBTRF/DPBTRF).
6:	LDAB – INTEGER Input
	<i>On entry</i> : the first dimension of the array AB as declared in the (sub)program from which F07HHF (SPBRFS/DPBRFS) is called.
	Constraint: $LDAB \ge KD + 1$.
7:	AFB(LDAFB,*) – <i>real</i> array Input
	Note: the second dimension of the array AFB must be at least $max(1, N)$.
	On entry: the Cholesky factor of A, as returned by F07HDF (SPBTRF/DPBTRF).
8:	LDAFB – INTEGER Input
	<i>On entry</i> : the first dimension of the array AFB as declared in the (sub)program from which F07HHF (SPBRFS/DPBRFS) is called.
	<i>Constraint</i> : $LDAFB \ge KD + 1$.
9:	B(LDB,*) – <i>real</i> array Input
	Note: the second dimension of the array B must be at least $max(1, NRHS)$.
	On entry: the n by r right-hand side matrix B .

On entry: the first dimension of the array B as declared in the (sub)program from which F07HHF (SPBRFS/DPBRFS) is called.

Constraint: $LDB \ge max(1, N)$.

11: X(LDX,*) – *real* array

LDB - INTEGER

10:

Note: the second dimension of the array X must be at least max(1, NRHS).

On entry: the n by r solution matrix X, as returned by F07HEF (SPBTRS/DPBTRS).

On exit: the improved solution matrix X.

12: LDX – INTEGER

On entry: the first dimension of the array X as declared in the (sub)program from which F07HHF (SPBRFS/DPBRFS) is called.

Constraint: $LDX \ge max(1, N)$.

13: FERR(*) – *real* array

Note: the dimension of the array FERR must be at least max(1, NRHS).

On exit: FERR(j) contains an estimated error bound for the *j*th solution vector, that is, the *j*th column of X, for j = 1, 2, ..., r.

14: BERR(*) – *real* array

Note: the dimension of the array BERR must be at least max(1, NRHS).

On exit: BERR(j) contains the component-wise backward error bound β for the *j*th solution vector, that is, the *j*th column of X, for j = 1, 2, ..., r.

15: WORK(*) - *real* array

Note: the dimension of the array WORK must be at least max(1, 3 * N).

16: IWORK(*) – INTEGER array

Note: the dimension of the array IWORK must be at least max(1, N).

17: INFO – INTEGER

On exit: INFO = 0 unless the routine detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the routine:

INFO < 0

If INFO = -i, the *i*th parameter had an illegal value. An explanatory message is output, and execution of the program is terminated.

7 Accuracy

The bounds returned in FERR are not rigorous, because they are estimated, not computed exactly; but in practice they almost always overestimate the actual error.

Input

Input

Output

Output

Input/Output

Workspace

Workspace

Output

8 **Further Comments**

For each right-hand side, computation of the backward error involves a minimum of 8nk floating-point operations. Each step of iterative refinement involves an additional 12nk operations. This assumes $n \gg k$. At most 5 steps of iterative refinement are performed, but usually only 1 or 2 steps are required.

Estimating the forward error involves solving a number of systems of linear equations of the form Ax = b; the number is usually 4 or 5 and never more than 11. Each solution involves approximately 4nk operations.

The complex analogue of this routine is F07HVF (CPBRFS/ZPBRFS).

9 Example

To solve the system of equations AX = B using iterative refinement and to compute the forward and backward error bounds, where

A =	(5.49	2.68	0.00	0.00	١		/ 22.09	5.10).
				0.00	and	B =	9.31	30.81	
	0.00	-2.39	2.60	-2.22	and		-5.24	-25.82	
	0.00			5.17	/		11.83	22.90	

Here A is symmetric and positive-definite, and is treated as a band matrix, which must first be factorized by F07HDF (SPBTRF/DPBTRF).

9.1 Program Text

Note: the listing of the example program presented below uses *bold italicised* terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
FO7HHF Example Program Text
*
     Mark 15 Release. NAG Copyright 1991.
*
*
      .. Parameters ..
      INTEGER
                       NIN, NOUT
                       (NIN=5,NOUT=6)
     PARAMETER
     real
                       ZERO
     PARAMETER
                      (ZERO=0.0e0)
     INTEGER
                      NMAX, NRHMAX, KDMAX, LDAB, LDAFB, LDB, LDX
     PARAMETER
                      (NMAX=8, NRHMAX=NMAX, KDMAX=8, LDAB=KDMAX+1,
     +
                      LDAFB=KDMAX+1,LDB=NMAX,LDX=NMAX)
      .. Local Scalars ..
                 I, IFAIL, INFO, J, KD, N, NRHS
     TNTEGER
      CHARACTER
                       UPLO
*
      .. Local Arrays ..
                       AB(LDAB,NMAX), AFB(LDAFB,NMAX), B(LDB,NRHMAX),
     real
     +
                       BERR(NRHMAX), FERR(NRHMAX), WORK(3*NMAX),
     +
                       X(LDX,NMAX)
     INTEGER
                      IWORK(NMAX)
      .. External Subroutines ..
*
                     F06QFF, F06QHF, spbrfs, spbtrf, spbtrs, X04CAF
     EXTERNAL
*
      .. Intrinsic Functions ..
      INTRINSIC
                      MAX, MIN
      .. Executable Statements ..
*
     WRITE (NOUT, *) 'FO7HHF Example Program Results'
     Skip heading in data file
*
     READ (NIN, *)
     READ (NIN, *) N, KD, NRHS
     IF (N.LE.NMAX .AND. KD.LE.KDMAX .AND. NRHS.LE.NRHMAX) THEN
*
*
         Set A to zero to avoid referencing uninitialized elements
*
         CALL F06QHF('General',KD+1,N,ZERO,ZERO,AB,LDAB)
*
*
         Read A and B from data file, and copy A to AFB and B to X
         READ (NIN, *) UPLO
         IF (UPLO.EQ.'U') THEN
```

```
DO 20 I = 1, N
                READ (NIN, \star) (AB(KD+1+I-J,J), J=I,MIN(N,I+KD))
   20
             CONTINUE
         ELSE IF (UPLO.EQ.'L') THEN
            DO 40 I = 1, N
                READ (NIN, \star) (AB(1+I-J,J), J=MAX(1,I-KD),I)
   40
             CONTINUE
         END IF
         READ (NIN, \star) ((B(I,J), J=1, NRHS), I=1, N)
*
         CALL F06QFF('General', KD+1, N, AB, LDAB, AFB, LDAFB)
*
         CALL F06QFF('General', N, NRHS, B, LDB, X, LDX)
*
         Factorize A in the array AFB
*
         CALL spbtrf(UPLO, N, KD, AFB, LDAFB, INFO)
*
         WRITE (NOUT, *)
         IF (INFO.EQ.0) THEN
*
*
             Compute solution in the array X
*
             CALL spbtrs(UPLO, N, KD, NRHS, AFB, LDAFB, X, LDX, INFO)
*
*
             Improve solution, and compute backward errors and
*
             estimated bounds on the forward errors
             CALL spbrfs(UPLO, N, KD, NRHS, AB, LDAB, AFB, LDAFB, B, LDB, X, LDX,
     +
                          FERR, BERR, WORK, IWORK, INFO)
*
             Print solution
*
*
             TFATL = 0
             CALL X04CAF('General',' ',N,NRHS,X,LDX,'Solution(s)',IFAIL)
*
             WRITE (NOUT, *)
             WRITE (NOUT,*) 'Backward errors (machine-dependent)'
             WRITE (NOUT, 99999) (BERR(J), J=1, NRHS)
             WRITE (NOUT, *)
               'Estimated forward error bounds (machine-dependent)'
     +
             WRITE (NOUT, 99999) (FERR(J), J=1, NRHS)
         ELSE
             WRITE (NOUT, *) 'A is not positive-definite'
         END IF
      END IF
      STOP
*
99999 FORMAT ((3X, 1P, 7e11.1))
      END
```

9.2 Program Data

FO7HHF Example Program Data :Values of N, KD and NRHS 4 1 2 'T.' :Value of UPLO 5.49 5.63 2.68 -2.39 2.60 5.17 -2.22 :End of matrix A 22.09 5.10 9.31 30.81 -5.24 -25.82 11.83 22.90 :End of matrix B

9.3 Program Results

FO7HHF Example Program Results

```
Solution(s)

1 2

1 5.0000 -2.0000

2 -2.0000 6.0000

3 -3.0000 -1.0000

4 1.0000 4.0000

Backward errors (machine-dependent)

4.9E-17 6.1E-17

Estimated forward error bounds (machine-dependent)

2.0E-14 3.0E-14
```