NAG Fortran Library Routine Document F07AVF (CGERFS/ZGERFS)

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of **bold italicised** terms and other implementation-dependent details.

1 Purpose

F07AVF (CGERFS/ZGERFS) returns error bounds for the solution of a complex system of linear equations with multiple right-hand sides, AX = B, $A^TX = B$ or $A^HX = B$. It improves the solution by iterative refinement, in order to reduce the backward error as much as possible.

2 Specification

```
SUBROUTINE F07AVF(TRANS, N, NRHS, A, LDA, AF, LDAF, IPIV, B, LDB, X, LDX, FERR, BERR, WORK, RWORK, INFO)

ENTRY cgerfs (TRANS, N, NRHS, A, LDA, AF, LDAF, IPIV, B, LDB, X, LDX, FERR, BERR, WORK, RWORK, INFO)

INTEGER N, NRHS, LDA, LDAF, IPIV(*), LDB, LDX, INFO

real FERR(*), BERR(*), RWORK(*)

complex (LDA, *), AF(LDAF, *), B(LDB, *), X(LDX, *), WORK(*)

CHARACTER*1
```

The ENTRY statement enables the routine to be called by its LAPACK name.

3 Description

This routine returns the backward errors and estimated bounds on the forward errors for the solution of a complex system of linear equations with multiple right-hand sides AX = B, $A^TX = B$ or $A^HX = B$. The routine handles each right-hand side vector (stored as a column of the matrix B) independently, so we describe the function of the routine in terms of a single right-hand side b and solution x.

Given a computed solution x, the routine computes the *component-wise backward error* β . This is the size of the smallest relative perturbation in each element of A and b such that x is the exact solution of a perturbed system

$$\begin{split} (A+\delta A)x &= b+\delta b\\ |\delta a_{ij}| &\leq \beta |a_{ij}| \quad \text{and} \quad |\delta b_i| \leq \beta |b_i|. \end{split}$$

Then the routine estimates a bound for the *component-wise forward error* in the computed solution, defined by:

$$\max_i |x_i - \hat{\pmb{x}}_i|/\max_i |x_i|$$

where \hat{x} is the true solution.

For details of the method, see the F07 Chapter Introduction.

4 References

Golub G H and van Loan C F (1996) Matrix Computations (3rd Edition) Johns Hopkins University Press, Baltimore

5 Parameters

1: TRANS - CHARACTER*1

Input

On entry: indicates the form of the linear equations for which X is the computed solution as follows:

if TRANS = 'N', the linear equations are of the form AX = B;

if TRANS = 'T', the linear equations are of the form $A^TX = B$;

if TRANS = 'C', the linear equations are of the form $A^{H}X = B$.

Constraint: TRANS = 'N', 'T' or 'C'.

2: N – INTEGER

Input

On entry: n, the order of the matrix A.

Constraint: N > 0.

3: NRHS – INTEGER

Input

On entry: r, the number of right-hand sides.

Constraint: NRHS ≥ 0 .

4: A(LDA,*) - complex array

Input

Note: the second dimension of the array A must be at least max(1, N).

On entry: the n by n original matrix A as supplied to F07ARF (CGETRF/ZGETRF).

5: LDA – INTEGER

Input

On entry: the first dimension of the array A as declared in the (sub)program from which F07AVF (CGERFS/ZGERFS) is called.

Constraint: LDA $\geq \max(1, N)$.

6: AF(LDAF,*) - complex array

Input

Note: the second dimension of the array AF must be at least max(1, N).

On entry: the LU factorization of A, as returned by F07ARF (CGETRF/ZGETRF).

7: LDAF – INTEGER

Input

On entry: the first dimension of the array AF as declared in the (sub)program from which F07AVF (CGERFS/ZGERFS) is called.

Constraint: LDAF $\geq \max(1, N)$.

8: IPIV(*) – INTEGER array

Input

Note: the dimension of the array IPIV must be at least max(1, N).

On entry: the pivot indices, as returned by F07ARF (CGETRF/ZGETRF).

9: B(LDB,*) - complex array

Input

Note: the second dimension of the array B must be at least max(1, NRHS).

On entry: the n by r right-hand side matrix B.

10: LDB - INTEGER

Input

On entry: the first dimension of the array B as declared in the (sub)program from which F07AVF (CGERFS/ZGERFS) is called.

Constraint: LDB $\geq \max(1, N)$.

11: X(LDX,*) - complex array

Input/Output

Note: the second dimension of the array X must be at least max(1, NRHS).

On entry: the n by r solution matrix X, as returned by F07ASF (CGETRS/ZGETRS).

On exit: the improved solution matrix X.

12: LDX – INTEGER

Input

On entry: the first dimension of the array X as declared in the (sub)program from which F07AVF (CGERFS/ZGERFS) is called.

Constraint: LDX $> \max(1, N)$.

13: FERR(*) - real array

Output

Note: the dimension of the array FERR must be at least max(1, NRHS).

On exit: FERR(j) contains an estimated error bound for the jth solution vector, that is, the jth column of X, for j = 1, 2, ..., r.

14: BERR(*) – real array

Output

Note: the dimension of the array BERR must be at least max(1, NRHS).

On exit: BERR(j) contains the component-wise backward error bound β for the jth solution vector, that is, the jth column of X, for j = 1, 2, ..., r.

15: WORK(*) - complex array

Workspace

Note: the dimension of the array WORK must be at least max(1, 2 * N).

16: RWORK(*) – *real* array

Workspace

Note: the dimension of the array RWORK must be at least max(1, N).

17: INFO – INTEGER

Output

On exit: INFO = 0 unless the routine detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the routine:

INFO < 0

If INFO = -i, the *i*th parameter had an illegal value. An explanatory message is output, and execution of the program is terminated.

7 Accuracy

The bounds returned in FERR are not rigorous, because they are estimated, not computed exactly; but in practice they almost always overestimate the actual error.

8 Further Comments

For each right-hand side, computation of the backward error involves a minimum of $16n^2$ real floating-point operations. Each step of iterative refinement involves an additional $24n^2$ real operations. At most 5 steps of iterative refinement are performed, but usually only 1 or 2 steps are required.

Estimating the forward error involves solving a number of systems of linear equations of the form Ax = b or $A^{H}x = b$; the number is usually 5 and never more than 11. Each solution involves approximately $8n^2$ real operations.

The real analogue of this routine is F07AHF (SGERFS/DGERFS).

9 Example

To solve the system of equations AX = B using iterative refinement and to compute the forward and backward error bounds, where

$$A = \begin{pmatrix} -1.34 + 2.55i & 0.28 + 3.17i & -6.39 - 2.20i & 0.72 - 0.92i \\ -0.17 - 1.41i & 3.31 - 0.15i & -0.15 + 1.34i & 1.29 + 1.38i \\ -3.29 - 2.39i & -1.91 + 4.42i & -0.14 - 1.35i & 1.72 + 1.35i \\ 2.41 + 0.39i & -0.56 + 1.47i & -0.83 - 0.69i & -1.96 + 0.67i \end{pmatrix}$$

and

$$B = \begin{pmatrix} 26.26 + 51.78i & 31.32 - 6.70i \\ 6.43 - 8.68i & 15.86 - 1.42i \\ -5.75 + 25.31i & -2.15 + 30.19i \\ 1.16 + 2.57i & -2.56 + 7.55i \end{pmatrix}.$$

Here A is nonsymmetric and must first be factorized by F07ARF (CGETRF/ZGETRF).

9.1 Program Text

Note: the listing of the example program presented below uses **bold italicised** terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
FO7AVF Example Program Text
      Mark 15 Release. NAG Copyright 1991.
      .. Parameters ..
                     NIN, NOUT
      TNTEGER
      PARAMETER
                       (NIN=5,NOUT=6)
                      NMAX, NRHMAX, LDA, LDAF, LDB, LDX
      INTEGER
                       (NMAX=8, NRHMAX=NMAX, LDA=NMAX, LDAF=NMAX, LDB=NMAX,
      PARAMETER
                      LDX=NMAX)
                 TRANS
(TRANS='N')
      CHARACTER
      PARAMETER
      .. Local Scalars ..
      INTEGER
                       I, IFAIL, INFO, J, N, NRHS
      .. Local Arrays ..
      complex A(LDA,NMAX), AF(LDAF,NMAX), B(LDB,NRHMAX), WORK(2*NMAX), X(LDX,NMAX)
      realBERR(NRHMAX), FERRINTEGERIPIV(NMAX)CHARACTERCLABS(1), RLABS(1)
                      BERR(NRHMAX), FERR(NRHMAX), RWORK(NMAX)
      .. External Subroutines ..
      EXTERNAL cgerfs, cgetrf, cgetrs, F06TFF, X04DBF
      .. Executable Statements ..
      WRITE (NOUT,*) 'F07AVF Example Program Results'
      Skip heading in data file
      READ (NIN, *)
      READ (NIN, *) N, NRHS
      IF (N.LE.NMAX .AND. NRHS.LE.NRHMAX) THEN
         Read A and B from data file, and copy A to AF and B to X
*
         READ (NIN, *) ((A(I,J), J=1, N), I=1, N)
```

```
READ (NIN,*) ((B(I,J),J=1,NRHS),I=1,N)
         CALL F06TFF('General',N,N,A,LDA,AF,LDAF)
         CALL F06TFF('General', N, NRHS, B, LDB, X, LDX)
         Factorize A in the array AF
        CALL cgetrf(N,N,AF,LDAF,IPIV,INFO)
        WRITE (NOUT, *)
        IF (INFO.EQ.O) THEN
           Compute solution in the array X
           CALL cgetrs(TRANS, N, NRHS, AF, LDAF, IPIV, X, LDX, INFO)
           Improve solution, and compute backward errors and
           estimated bounds on the forward errors
           CALL cgerfs (TRANS, N, NRHS, A, LDA, AF, LDAF, IPIV, B, LDB, X, LDX,
     +
                        FERR, BERR, WORK, RWORK, INFO)
           Print solution
           IFAIL = 0
           80,0,IFAIL)
           WRITE (NOUT, *)
           WRITE (NOUT,*) 'Backward errors (machine-dependent)'
           WRITE (NOUT, 99999) (BERR(J), J=1, NRHS)
           WRITE (NOUT, *)
              'Estimated forward error bounds (machine-dependent)'
           WRITE (NOUT, 99999) (FERR(J), J=1, NRHS)
         ELSE
           WRITE (NOUT, *) 'The factor U is singular'
        END IF
     END IF
     STOP
99999 FORMAT ((5X,1P,4(e11.1,7X)))
     END
```

9.2 Program Data

```
FO7AVF Example Program Data
4 2 :Values of N and NRHS
(-1.34, 2.55) ( 0.28, 3.17) (-6.39,-2.20) ( 0.72,-0.92)
(-0.17,-1.41) ( 3.31,-0.15) (-0.15, 1.34) ( 1.29, 1.38)
(-3.29,-2.39) (-1.91, 4.42) (-0.14,-1.35) ( 1.72, 1.35)
( 2.41, 0.39) (-0.56, 1.47) (-0.83,-0.69) (-1.96, 0.67) :End of matrix A
(26.26, 51.78) (31.32, -6.70)
( 6.43, -8.68) (15.86, -1.42)
(-5.75, 25.31) (-2.15, 30.19)
( 1.16, 2.57) (-2.56, 7.55) :End of matrix B
```

9.3 Program Results

```
FO7AVF Example Program Results

Solution(s)

1 2

1 (1.0000, 1.0000) (-1.0000, -2.0000)
2 (2.0000, -3.0000) (5.0000, 1.0000)
3 (-4.0000, -5.0000) (-3.0000, 4.0000)
4 (0.0000, 6.0000) (2.0000, -3.0000)

Backward errors (machine-dependent)
9.1E-17 7.2E-17

Estimated forward error bounds (machine-dependent)
5.9E-14 7.6E-14
```