NAG Fortran Library Routine Document

E02AJF

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of **bold italicised** terms and other implementation-dependent details.

1 Purpose

E02AJF determines the coefficients in the Chebyshev-series representation of the indefinite integral of a polynomial given in Chebyshev-series form.

2 Specification

```
SUBROUTINE E02AJF(NP1, XMIN, XMAX, A, IA1, LA, QATM1, AINT, IAINT1,

LAINT, IFAIL)

INTEGER NP1, IA1, LA, IAINT1, LAINT, IFAIL

real XMIN, XMAX, A(LA), QATM1, AINT(LAINT)
```

3 Description

This routine forms the polynomial which is the indefinite integral of a given polynomial. Both the original polynomial and its integral are represented in Chebyshev-series form. If supplied with the coefficients a_i , for i = 0, 1, ..., n, of a polynomial p(x) of degree n, where

$$p(x) = \frac{1}{2}a_0 + a_1T_1(\bar{x}) + \dots + a_nT_n(\bar{x}),$$

the routine returns the coefficients a'_i , for $i=0,1,\ldots,n+1$, of the polynomial q(x) of degree n+1, where

$$q(x) = \frac{1}{2}a'_0 + a'_1T_1(\bar{x}) + \dots + a'_{n+1}T_{n+1}(\bar{x}),$$

and

$$q(x) = \int p(x) \, dx.$$

Here $T_j(\bar{x})$ denotes the Chebyshev polynomial of the first kind of degree j with argument \bar{x} . It is assumed that the normalised variable \bar{x} in the interval [-1,+1] was obtained from the user's original variable x in the interval $[x_{\min},x_{\max}]$ by the linear transformation

$$\bar{x} = \frac{2x - (x_{\text{max}} + x_{\text{min}})}{x_{\text{max}} - x_{\text{min}}}$$

and that the user requires the integral to be with respect to the variable x. If the integral with respect to \bar{x} is required, set $x_{\max} = 1$ and $x_{\min} = -1$.

Values of the integral can subsequently be computed, from the coefficients obtained, by using E02AKF.

The method employed is that of Chebyshev-series (see Chapter 8 of NPL (1961)), modified for integrating with respect to x. Initially taking $a_{n+1} = a_{n+2} = 0$, the routine forms successively

$$a_i' = \frac{a_{i-1} - a_{i+1}}{2i} \times \frac{x_{\max} - x_{\min}}{2}, \quad i = n+1, n, \dots, 1.$$

The constant coefficient a_0' is chosen so that q(x) is equal to a specified value, QATM1, at the lower endpoint of the interval on which it is defined, i.e., $\bar{x} = -1$, which corresponds to $x = x_{\min}$.

4 References

NPL (1961) Chebyshev-series *Modern Computing Methods, NPL Notes on Applied Science* **16** (2nd Edition) HMSO

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5 Parameters

1: NP1 – INTEGER Input

On entry: n + 1, where n is the degree of the given polynomial p(x). Thus NP1 is the number of coefficients in this polynomial.

Constraint: NP1 \geq 1.

2: XMIN - real
 3: XMAX - real
 Input

On entry: the lower and upper end-points respectively of the interval $[x_{\min}, x_{\max}]$. The Chebyshev-series representation is in terms of the normalised variable \bar{x} , where

$$\bar{x} = \frac{2x - (x_{\text{max}} + x_{\text{min}})}{x_{\text{max}} - x_{\text{min}}}.$$

Constraint: XMAX > XMIN.

4: A(LA) - real array

Input

On entry: the Chebyshev coefficients of the polynomial p(x). Specifically, element $1 + i \times IA1$ of A must contain the coefficient a_i , for i = 0, 1, ..., n. Only these n + 1 elements will be accessed. Unchanged on exit, but see AINT, below.

5: IA1 – INTEGER Input

On entry: the index increment of A. Most frequently the Chebyshev coefficients are stored in adjacent elements of A, and IA1 must be set to 1. However, if for example, they are stored in $A(1), A(4), A(7), \ldots$, then the value of IA1 must be 3. See also Section 8.

Constraint: IA1 ≥ 1 .

6: LA – INTEGER Input

On entry: the dimension of the array A as declared in the (sub)program from which E02AJF is called.

Constraint: LA $\geq 1 + (NP1 - 1) \times IA1$.

7: QATM1 – real Input

On entry: the value that the integrated polynomial is required to have at the lower end-point of its interval of definition, i.e., at $\bar{x}=-1$ which corresponds to $x=x_{\min}$. Thus, QATM1 is a constant of integration and will normally be set to zero by the user.

8: AINT(LAINT) – real array Output

On exit: the Chebyshev coefficients of the integral q(x). (The integration is with respect to the variable x, and the constant coefficient is chosen so that $q(x_{\min})$ equals QATM1). Specifically, element $1+i \times \text{IAINT1}$ of AINT contains the coefficient a_i' , for $i=0,1,\ldots,n+1$. A call of the routine may have the array name AINT the same as A, provided that note is taken of the order in which elements are overwritten when choosing starting elements and increments IA1 and IAINT1: i.e., the coefficients, $a_0, a_1, \ldots, a_{i-2}$ must be intact after coefficient a_i' is stored. In particular it is possible to overwrite the a_i entirely by having IA1 = IAINT1, and the actual array for A and AINT identical.

9: IAINT1 – INTEGER Input

On entry: the index increment of AINT. Most frequently the Chebyshev coefficients are required in adjacent elements of AINT, and IAINT1 must be set to 1. However, if, for example, they are to be stored in AINT(1), AINT(4), AINT(7),..., then the value of IAINT1 must be 3. See also Section 8.

Constraint: IAINT1 ≥ 1 .

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10: LAINT - INTEGER

Input

On entry: the dimension of the array AINT as declared in the (sub)program from which E02AJF is called.

Constraint: LAINT $\geq 1 + NP1 \times IAINT1$.

11: IFAIL – INTEGER

Input/Output

On entry: IFAIL must be set to 0, -1 or 1. Users who are unfamiliar with this parameter should refer to Chapter P01 for details.

On exit: IFAIL = 0 unless the routine detects an error (see Section 6).

For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, for users not familiar with this parameter the recommended value is 0. When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.

6 Error Indicators and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

```
IFAIL = 1
```

```
\begin{array}{lll} \text{On entry, } & NP1 < 1, \\ \text{or } & XMAX \leq XMIN, \\ \text{or } & IA1 < 1, \\ \text{or } & LA \leq (NP1-1) \times IA1, \\ \text{or } & IAINT1 < 1, \\ \text{or } & LAINT \leq NP1 \times IAINT1. \end{array}
```

7 Accuracy

In general there is a gain in precision in numerical integration, in this case associated with the division by 2i in the formula quoted in Section 3.

8 Further Comments

The time taken by the routine is approximately proportional to n+1.

The increments IA1, IAINT1 are included as parameters to give a degree of flexibility which, for example, allows a polynomial in two variables to be integrated with respect to either variable without rearranging the coefficients.

9 Example

Suppose a polynomial has been computed in Chebyshev-series form to fit data over the interval [-0.5, 2.5]. The following program evaluates the integral of the polynomial from 0.0 to 2.0. (For the purpose of this example, XMIN, XMAX and the Chebyshev coefficients are simply supplied in DATA statements. Normally a program would read in or generate data and compute the fitted polynomial).

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9.1 Program Text

Note: the listing of the example program presented below uses *bold italicised* terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
E02AJF Example Program Text
     Mark 14 Revised. NAG Copyright 1989.
      .. Parameters ..
                       NP1, LA, LAINT
      INTEGER
                       (NP1=7,LA=NP1,LAINT=NP1+1)
     PARAMETER
      INTEGER
                       NOUT
                      (NOUT=6)
     PARAMETER
      .. Local Scalars ..
     real
                       RA, RB, RESULT, XA, XB, XMAX, XMIN
      INTEGER
                       I, IFAIL
      .. Local Arrays ..
                       A(LA), AINT(LAINT)
      .. External Subroutines ..
      EXTERNAL
                      EO2AJF, EO2AKF
      .. Data statements ..
     DATA
                       XMIN, XMAX/-0.5e0, 2.5e0/
                       (A(I), I=1, NP1)/2.53213e0, 1.13032e0, 0.27150e0,
     DATA
                       0.04434e0, 0.00547e0, 0.00054e0, 0.00004e0/
      .. Executable Statements ..
     WRITE (NOUT,*) 'E02AJF Example Program Results'
      IFAIL = 0
      CALL E02AJF(NP1,XMIN,XMAX,A,1,LA,0.0e0,AINT,1,LAINT,IFAIL)
      XA = 0.0e0
     XB = 2.0e0
      CALL EO2AKF(NP1+1,XMIN,XMAX,AINT,1,LAINT,XA,RA,IFAIL)
      CALL EO2AKF(NP1+1,XMIN,XMAX,AINT,1,LAINT,XB,RB,IFAIL)
     RESULT = RB - RA
      WRITE (NOUT, *)
     WRITE (NOUT, 99999) 'Value of definite integral is ', RESULT
99999 FORMAT (1X,A,F10.4)
     END
```

9.2 Program Data

None.

9.3 Program Results

```
E02AJF Example Program Results

Value of definite integral is 2.1515
```

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