NAG Fortran Library Routine Document

C06FRF

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of ***bold italicised*** terms and other implementation-dependent details.

1 Purpose

C06FRF computes the discrete Fourier transforms of m sequences, each containing n complex data values. This routine is designed to be particularly efficient on vector processors.

2 Specification

```
SUBROUTINE C06FRF(M, N, X, Y, INIT, TRIG, WORK, IFAIL)
INTEGER           M, N, IFAIL
real              X(M*N), Y(M*N), TRIG(2*N), WORK(2*M*N)
CHARACTER*1       INIT
```

3 Description

Given m sequences of n complex data values z_j^p, for $j = 0, 1, \ldots, n-1$; $p = 1, 2, \ldots, m$, this routine simultaneously calculates the Fourier transforms of all the sequences defined by:

$$\hat{z}_k^p = \frac{1}{\sqrt{n}} \sum_{j=0}^{n-1} z_j^p \times \exp\left(-i\frac{2\pi jk}{n}\right), \quad k = 0, 1, \ldots, n-1; \quad p = 1, 2, \ldots, m.$$

(Note the scale factor $\frac{1}{\sqrt{n}}$ in this definition.)

The discrete Fourier transform is sometimes defined using a positive sign in the exponential term

$$\hat{z}_k^p = \frac{1}{\sqrt{n}} \sum_{j=0}^{n-1} z_j^p \times \exp\left(+i\frac{2\pi jk}{n}\right).$$

To compute this form, this routine should be preceded and followed by a call of C06GCF to form the complex conjugates of the z_j^p and the $\hat{z}_k^p$.

The routine uses a variant of the fast Fourier transform (FFT) algorithm (Brigham (1974)) known as the Stockham self-sorting algorithm, which is described in Temperton (1983b). Special code is provided for the factors 2, 3, 4, 5 and 6. This routine is designed to be particularly efficient on vector processors, and it becomes especially fast as m, the number of transforms to be computed in parallel, increases.

4 References

Brigham E O (1974) *The Fast Fourier Transform* Prentice-Hall

Temperton C (1983b) Self-sorting mixed-radix fast Fourier transforms *J. Comput. Phys.* **52** 1–23

5 Parameters

1: M – INTEGER *Input*

On entry: the number of sequences to be transformed, m.

Constraint: M ≥ 1.

2: N – INTEGER *Input*

On entry: the number of complex values in each sequence, n.

Constraint: N ≥ 1.

3: X(M∗N) – ***real*** array *Input/Output*

4: Y(M∗N) – ***real*** array *Input/Output*

On entry: the real and imaginary parts of the complex data must be stored in X and Y respectively as if in a two-dimensional array of dimension $(1 : \mathrm{M}, 0 : \mathrm{N} - 1)$; each of the m sequences is stored in a **row** of each array. In other words, if the real parts of the pth sequence to be transformed are denoted by x_j^p, for $j = 0, 1, \ldots, n-1$, then the mn elements of the array X must contain the values

$$x_0^1, x_0^2, \ldots, x_0^m,\ x_1^1, x_1^2, \ldots, x_1^m, \ldots,\ x_{n-1}^1, x_{n-1}^2, \ldots, x_{n-1}^m.$$

On exit: X and Y are overwritten by the real and imaginary parts of the complex transforms.

5: INIT – CHARACTER*1 *Input*

On entry: if the trigonometric coefficients required to compute the transforms are to be calculated by the routine and stored in the array TRIG, then INIT must be set equal to 'I' (**I**nitial call).

If INIT contains 'S' (**S**ubsequent call), then the routine assumes that trigonometric coefficients for the specified value of n are supplied in the array TRIG, having been calculated in a previous call to one of C06FPF, C06FQF or C06FRF.

If INIT contains 'R' (**R**estart) then the routine assumes that trigonometric coefficients for the particular value of n are supplied in the array TRIG, but does not check that C06FPF, C06FQF or C06FRF have previously been called. This option allows the TRIG array to be stored in an external file, read in and re-used without the need for a call with INIT equal to 'I'. The routine carries out a simple test to check that the current value of n is compatible with the array TRIG.

Constraint: INIT = 'I', 'S' or 'R'.

6: TRIG(2∗N) – ***real*** array *Input/Output*

On entry: if INIT = 'S', or 'R', TRIG must contain the required coefficients calculated in a previous call of the routine. Otherwise TRIG need not be set.

On exit: TRIG contains the required coefficients (computed by the routine if INIT = 'I').

7: WORK(2∗M∗N) – ***real*** array *Workspace*

8: IFAIL – INTEGER *Input/Output*

On entry: IFAIL must be set to 0, -1 or 1. Users who are unfamiliar with this parameter should refer to Chapter P01 for details.

On exit: IFAIL = 0 unless the routine detects an error (see Section 6).

For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, for users not familiar with this parameter the recommended value is 0. **When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.**

6 Error Indicators and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

IFAIL = 1

On entry, M < 1.

IFAIL = 2

On entry, N < 1.

IFAIL = 3

On entry, INIT is not one of 'I', 'S' or 'R'.

IFAIL = 4

Not used at this Mark.

IFAIL = 5

On entry, INIT = 'S' or 'R', but the array TRIG and the current value of n are inconsistent.

IFAIL = 6

7 Accuracy

Some indication of accuracy can be obtained by performing a subsequent inverse transform and comparing the results with the original sequence (in exact arithmetic they would be identical).

8 Further Comments

The time taken by the routine is approximately proportional to $nm \times \log n$, but also depends on the factors of n. The routine is fastest if the only prime factors of n are 2, 3 and 5, and is particularly slow if n is a large prime, or has large prime factors.

9 Example

This program reads in sequences of complex data values and prints their discrete Fourier transforms (as computed by C06FRF). Inverse transforms are then calculated using C06GCF and C06FRF and printed out, showing that the original sequences are restored.

9.1 Program Text

Note: the listing of the example program presented below uses ***bold italicised*** terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
*     C06FRF Example Program Text
*     Mark 14 Revised.  NAG Copyright 1989.
*     .. Parameters ..
      INTEGER          MMAX, NMAX
      PARAMETER        (MMAX=5,NMAX=20)
      INTEGER          NIN, NOUT
      PARAMETER        (NIN=5,NOUT=6)
*     .. Local Scalars ..
      INTEGER          I, IFAIL, J, M, N
*     .. Local Arrays ..
      real             TRIG(2*NMAX), WORK(2*MMAX*NMAX), X(MMAX*NMAX),
     +                 Y(MMAX*NMAX)
*     .. External Subroutines ..
      EXTERNAL         C06FRF, C06GCF
*     .. Executable Statements ..
      WRITE (NOUT,*) 'C06FRF Example Program Results'
*     Skip heading in data file
      READ (NIN,*)
   20 READ (NIN,*,END=120) M, N
      IF (M.LE.MMAX .AND. N.LE.NMAX) THEN
         DO 40 J = 1, M
            READ (NIN,*) (X(I*M+J),I=0,N-1)
            READ (NIN,*) (Y(I*M+J),I=0,N-1)
   40    CONTINUE
```

```
         WRITE (NOUT,*)
         WRITE (NOUT,*) 'Original data values'
         DO 60 J = 1, M
            WRITE (NOUT,*)
            WRITE (NOUT,99999) 'Real ', (X(I*M+J),I=0,N-1)
            WRITE (NOUT,99999) 'Imag ', (Y(I*M+J),I=0,N-1)
   60    CONTINUE
         IFAIL = 0
*
         CALL C06FRF(M,N,X,Y,'Initial',TRIG,WORK,IFAIL)
*
         WRITE (NOUT,*)
         WRITE (NOUT,*) 'Discrete Fourier transforms'
         DO 80 J = 1, M
            WRITE (NOUT,*)
            WRITE (NOUT,99999) 'Real ', (X(I*M+J),I=0,N-1)
            WRITE (NOUT,99999) 'Imag ', (Y(I*M+J),I=0,N-1)
   80    CONTINUE
*
         CALL C06GCF(Y,M*N,IFAIL)
         CALL C06FRF(M,N,X,Y,'Subsequent',TRIG,WORK,IFAIL)
         CALL C06GCF(Y,M*N,IFAIL)
*
         WRITE (NOUT,*)
         WRITE (NOUT,*) 'Original data as restored by inverse transform'
         DO 100 J = 1, M
            WRITE (NOUT,*)
            WRITE (NOUT,99999) 'Real ', (X(I*M+J),I=0,N-1)
            WRITE (NOUT,99999) 'Imag ', (Y(I*M+J),I=0,N-1)
  100    CONTINUE
         GO TO 20
      ELSE
         WRITE (NOUT,*) 'Invalid value of M or N'
      END IF
  120 STOP
*
99999 FORMAT (1X,A,6F10.4)
      END
```

9.2 Program Data

```
C06FRF Example Program Data
     3     6
     0.3854    0.6772    0.1138    0.6751    0.6362    0.1424
     0.5417    0.2983    0.1181    0.7255    0.8638    0.8723
     0.9172    0.0644    0.6037    0.6430    0.0428    0.4815
     0.9089    0.3118    0.3465    0.6198    0.2668    0.1614
     0.1156    0.0685    0.2060    0.8630    0.6967    0.2792
     0.6214    0.8681    0.7060    0.8652    0.9190    0.3355
```

9.3 Program Results

```
 C06FRF Example Program Results

 Original data values

 Real     0.3854    0.6772    0.1138    0.6751    0.6362    0.1424
 Imag     0.5417    0.2983    0.1181    0.7255    0.8638    0.8723

 Real     0.9172    0.0644    0.6037    0.6430    0.0428    0.4815
 Imag     0.9089    0.3118    0.3465    0.6198    0.2668    0.1614

 Real     0.1156    0.0685    0.2060    0.8630    0.6967    0.2792
 Imag     0.6214    0.8681    0.7060    0.8652    0.9190    0.3355

 Discrete Fourier transforms

 Real     1.0737   -0.5706    0.1733   -0.1467    0.0518    0.3625
 Imag     1.3961   -0.0409   -0.2958   -0.1521    0.4517   -0.0321
```

```
 Real     1.1237    0.1728    0.4185    0.1530    0.3686    0.0101
 Imag     1.0677    0.0386    0.7481    0.1752    0.0565    0.1403

 Real     0.9100   -0.3054    0.4079   -0.0785   -0.1193   -0.5314
 Imag     1.7617    0.0624   -0.0695    0.0725    0.1285   -0.4335

 Original data as restored by inverse transform

 Real     0.3854    0.6772    0.1138    0.6751    0.6362    0.1424
 Imag     0.5417    0.2983    0.1181    0.7255    0.8638    0.8723

 Real     0.9172    0.0644    0.6037    0.6430    0.0428    0.4815
 Imag     0.9089    0.3118    0.3465    0.6198    0.2668    0.1614

 Real     0.1156    0.0685    0.2060    0.8630    0.6967    0.2792
 Imag     0.6214    0.8681    0.7060    0.8652    0.9190    0.3355
```